

# Real-time H.264 Video Coding for Telemedicine Applications

*short version + practical tasks*

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# About the presenter I

- H.264 video codec developer at the Fraunhofer Institute for Integrated Circuits in Erlangen, Germany in 2007 and 2008
- Graduated from Salzburg University of Applied Sciences in 2008
- Worked as IPTV software engineer until 2009
- Currently researching memory management optimization in H.264 video encoders

# About the presenter II

- Working at the department of Information Technology and Systems Management at the Salzburg University of Applied Sciences
- Research assistant in “Industrial information technology” group, focused on test management and generic data conversion
- Teaching Digital Technology and Microcontroller Programming laboratories as well as Applied Mathematics tutorials

# About the University I



# About the University II

- 18 departments in the following areas:
  - Information Technologies
  - Wood and Biogenic Technologies
  - Business and Tourism
  - Media and Design
  - Health and Social Work
- Department of Information Technology and Systems Management (ITS)

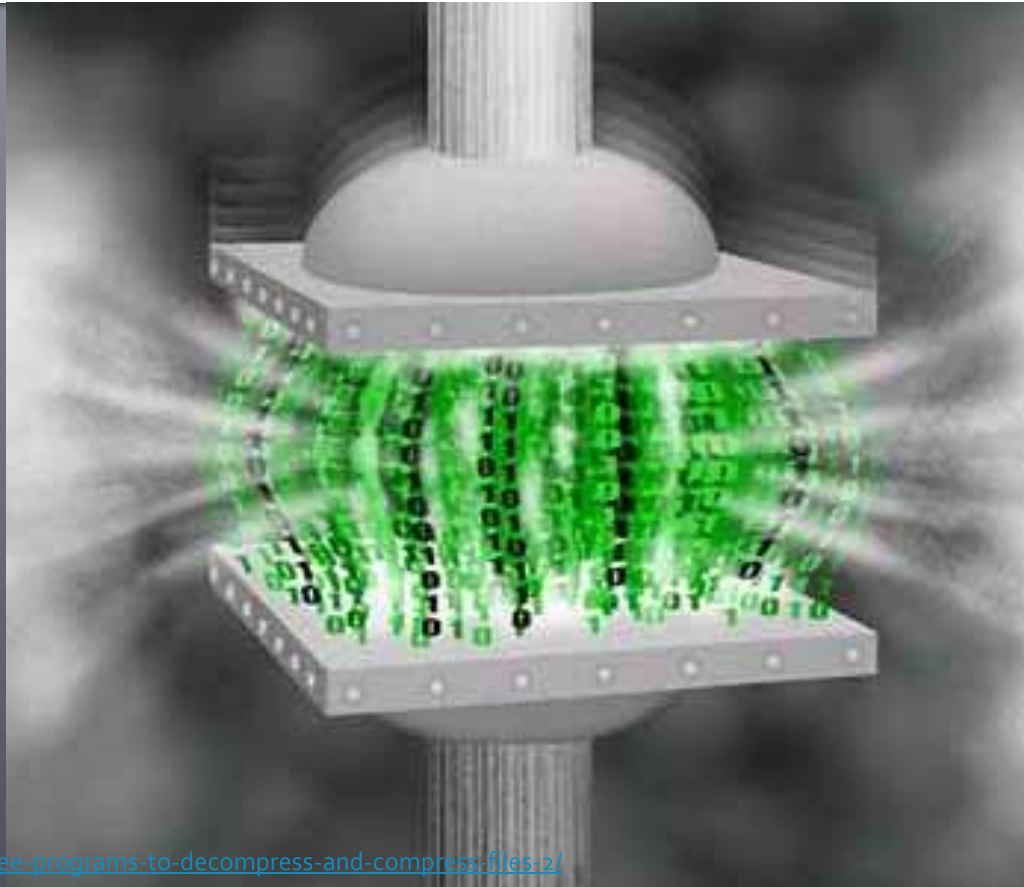
# About ITS

- Bachelor and Master degree programs
- Specializations (Master degree program)
  - Embedded Signal Processing
  - Adaptive Software Systems
  - Convergent Network and Mobility
  - E-Health
- Bachelor and Master exchange programs with ESIGETEL (→ separate presentation)

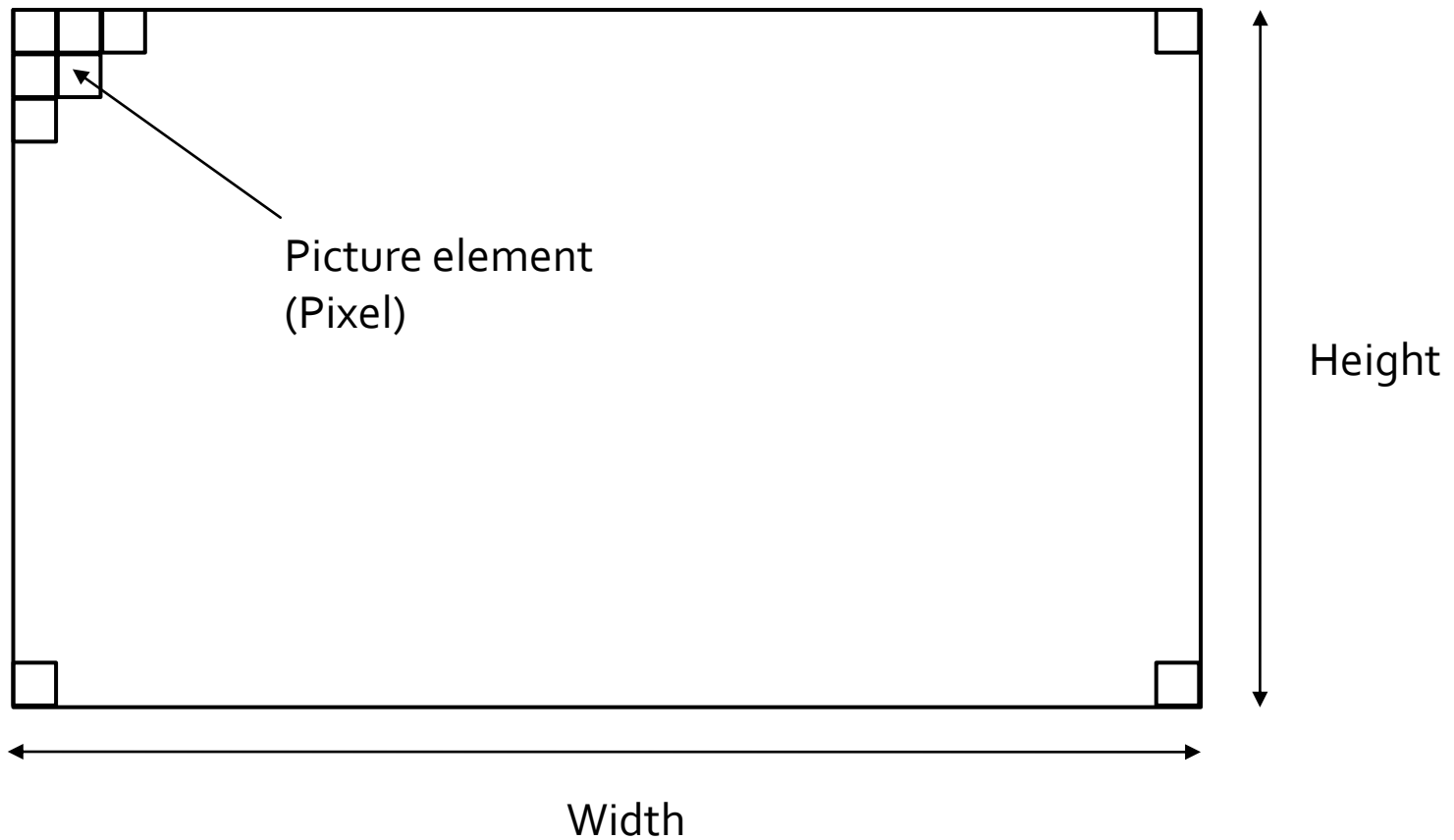
# Overview

- Introduction to image and video coding
- The H.264 standard
- Real-time aspects of H.264 video coding
- H.264 error resilience tools
- Practical work

# Introduction to image and video coding

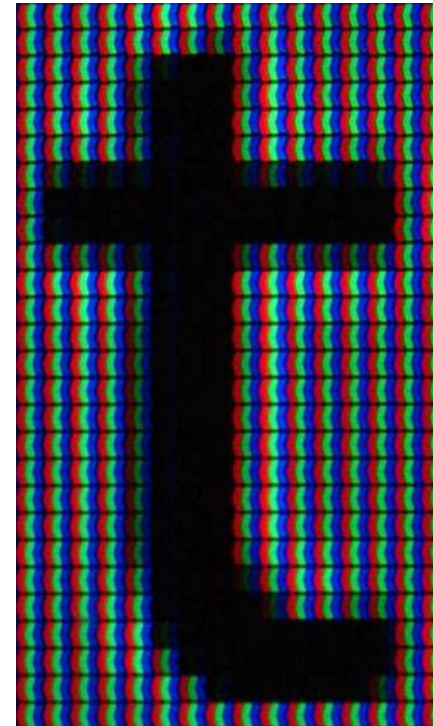
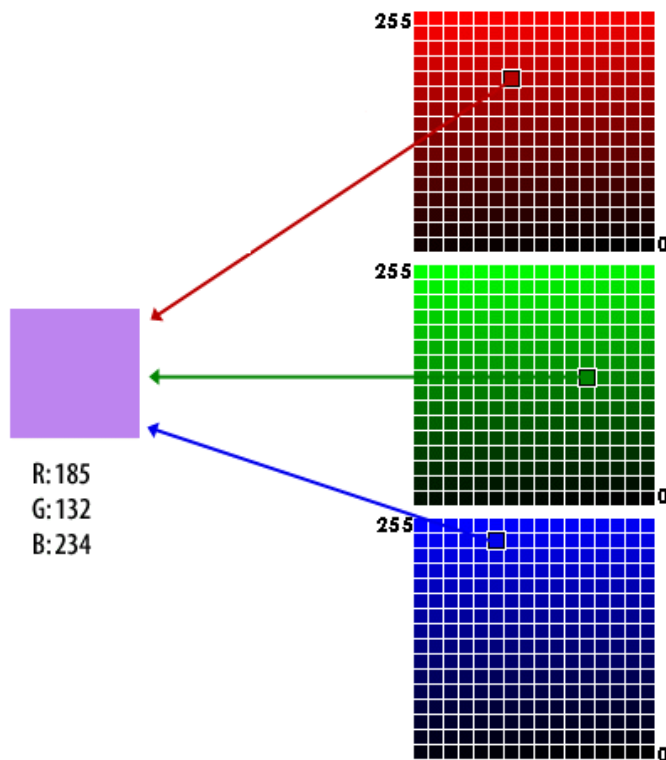


# Digital images



# Digital color images

- R, G and B information for each pixel
- Sum of components forms perceived color



# YUV color space

- Alternative representation of color information
- Luminance (Y) component and 2 color difference signals ( $U/C_B$  and  $V/C_R$ , “chroma”)
- Conversion from and to RGB possible
- Why?
  - Compatibility to black/white television signals (luminance only, no chroma)
  - Possibility to easily reduce chroma resolution as the human visual system is more sensitive to luma

# YUV images

Y



U



V

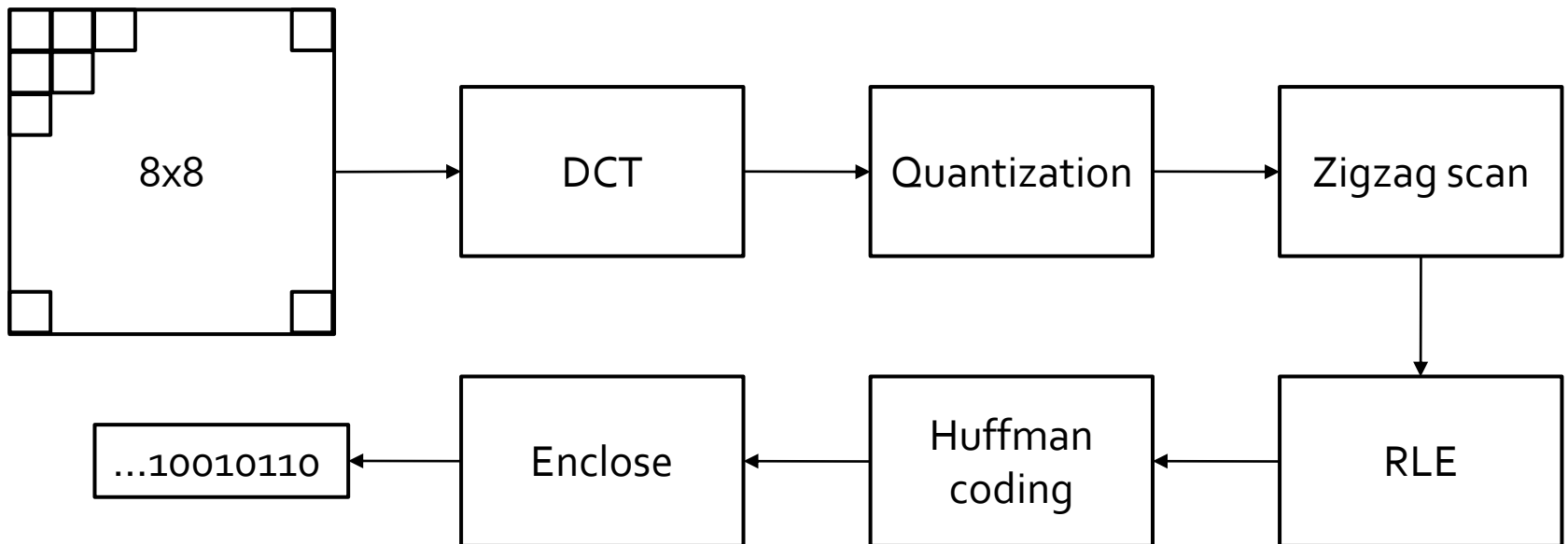


+ +



# JPEG image compression

- Image split into blocks of 8x8 luma samples (macroblocks)
- Each macroblock is processed separately



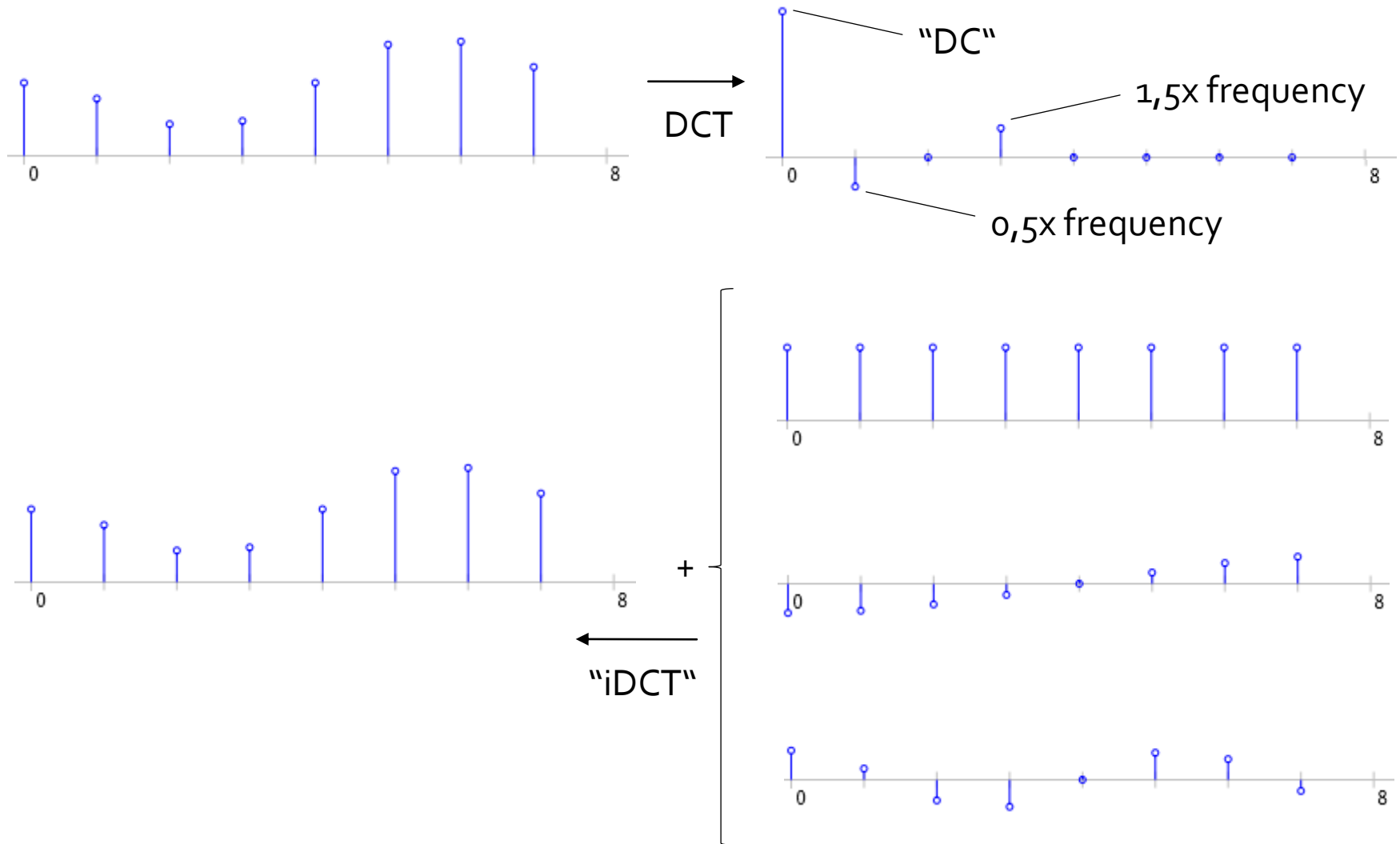
# 1D DCT

- Discrete cosine transform (one-dimensional)
- Transformation of signal to frequency domain
- Cosines of different frequencies as basis functions → weighted sum of bases forms signal

- DCT: 
$$X_k = \sum_{n=0}^{N-1} x_n \cos \left[ \frac{\pi}{N} \left( n + \frac{1}{2} \right) k \right] \quad k = 0, \dots, N$$

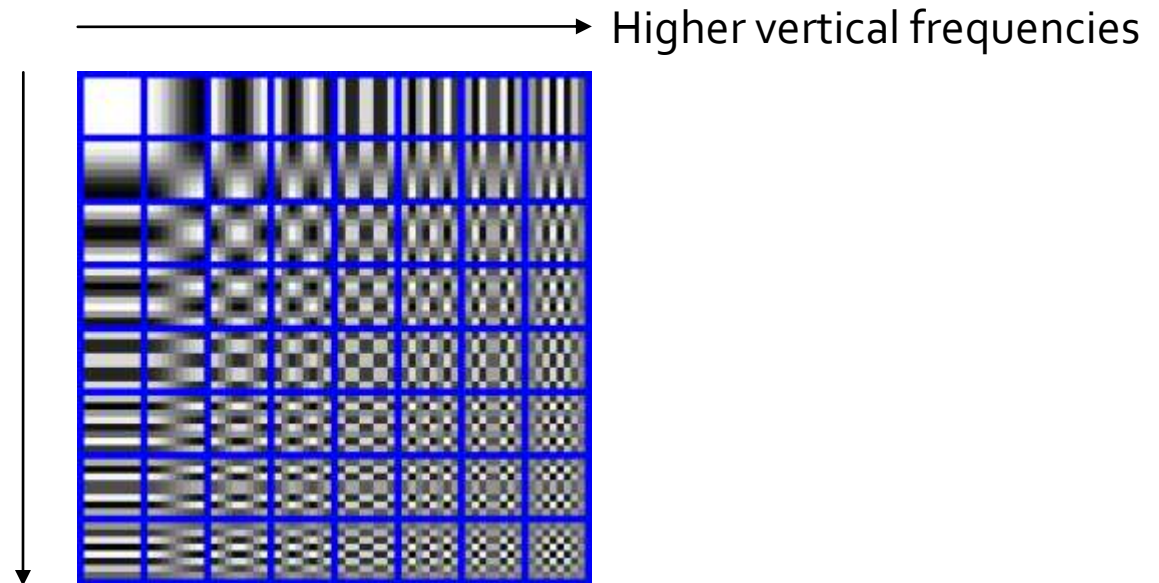
- iDCT 
$$X_k = \frac{1}{2} x_0 + \sum_{n=1}^{N-1} x_n \cos \left[ \frac{\pi}{N} n \left( k + \frac{1}{2} \right) \right]$$

# 1D DCT example



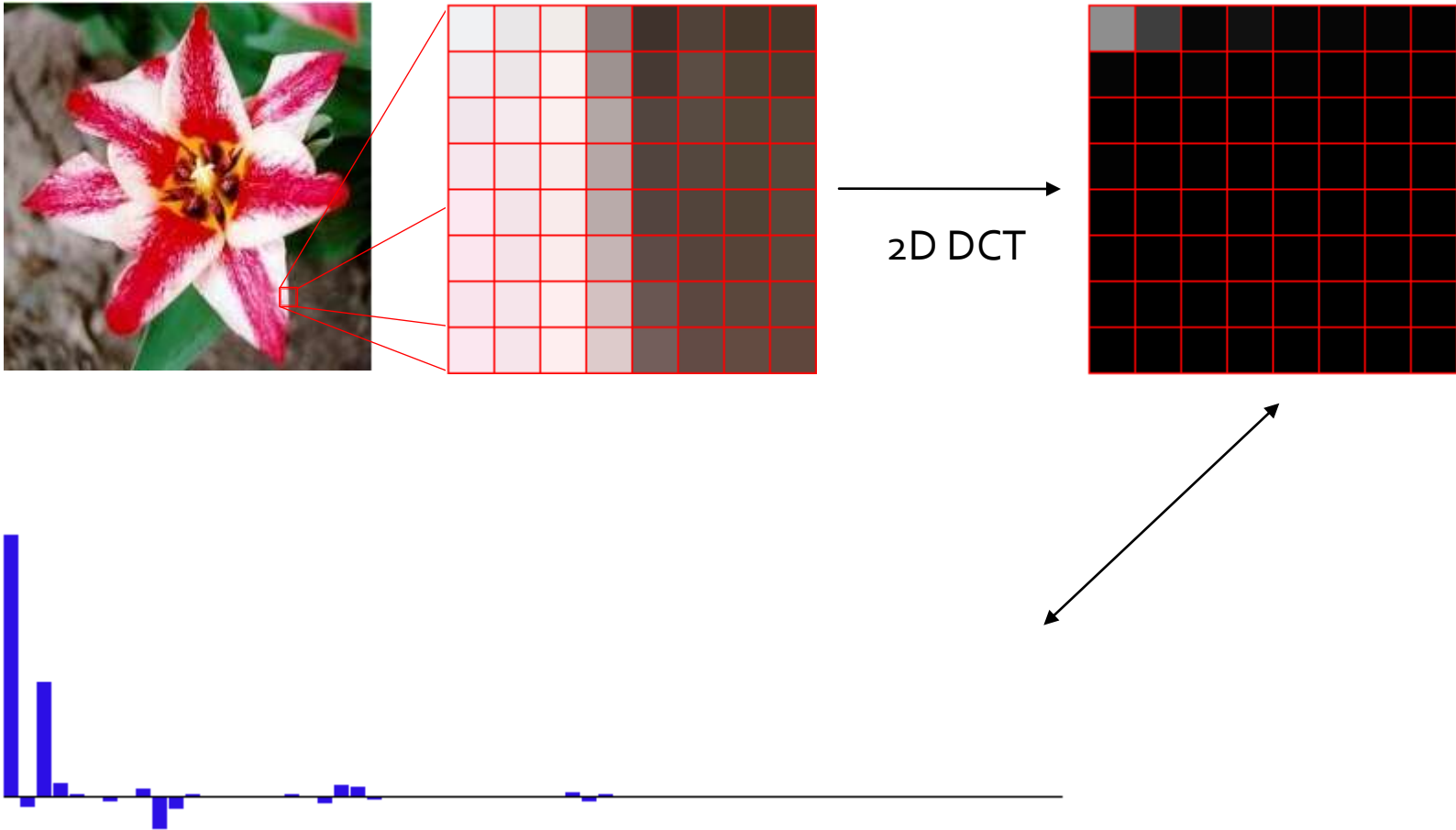
# 2D DCT

- Two-dimensional extension of 1D DCT
- Spatial frequencies in gray images: change of gray (signal) value per pixel
- Basis images:



Higher horizontal frequencies

# 2D DCT example



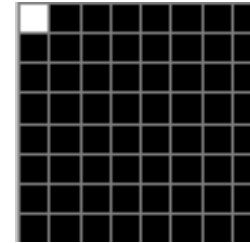
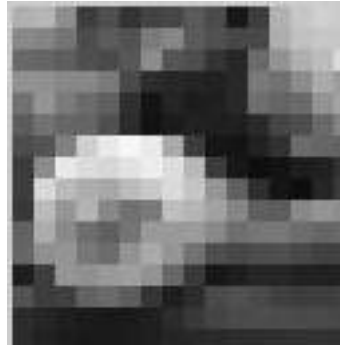
# DCT properties

- Theoretically lossless (beware of floating point rounding errors!)
- Decorrelates input signal → simplifies compression
- Human visual system merely perceives loss of high frequencies → simplifies compression
- JPEG's 2D DCT works on shifted input data (8 bit values are shifted to a  $[-128;127]$  range)

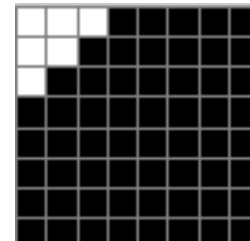
# Effect of high frequency loss



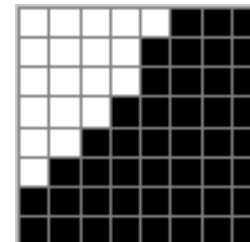
Original



1 DCT coefficient  
(all others zero)



6 DCT coefficients  
(all others zero)



19 DCT coefficients  
(all others zero)

# Quantization

- Reduce number of possible values instead of eliminating coefficients in transform domain
- Division by factor, followed by rounding → less bits required for representation
- Quantization matrix  $Q$  specifies division factors for every coefficient → higher quantization factors for higher frequencies

$$B_{j,k} = \text{round} \left( \frac{G_{j,k}}{Q_{j,k}} \right) \text{ for } j = 0, 1, 2, \dots, 7; k = 0, 1, 2, \dots, 7$$

# Quantization example

$$G = \begin{bmatrix} -415.38 & -30.19 & -61.20 & 27.24 & 56.13 & -20.10 & -2.39 & 0.46 \\ 4.47 & -21.86 & -60.76 & 10.25 & 13.15 & -7.09 & -8.54 & 4.88 \\ -46.83 & 7.37 & 77.13 & -24.56 & -28.91 & 9.93 & 5.42 & -5.65 \\ -48.53 & 12.07 & 34.10 & -14.76 & -10.24 & 6.30 & 1.83 & 1.95 \\ 12.12 & -6.55 & -13.20 & -3.95 & -1.88 & 1.75 & -2.79 & 3.14 \\ -7.73 & 2.91 & 2.38 & -5.94 & -2.38 & 0.94 & 4.30 & 1.85 \\ -1.03 & 0.18 & 0.42 & -2.42 & -0.88 & -3.02 & 4.12 & -0.66 \\ -0.17 & 0.14 & -1.07 & -4.19 & -1.17 & -0.10 & 0.50 & 1.68 \end{bmatrix}$$

Quantization with  $Q$  ↓

$$B = \begin{bmatrix} -26 & -3 & -6 & 2 & 2 & -1 & 0 & 0 \\ 0 & -2 & -4 & 1 & 1 & 0 & 0 & 0 \\ -3 & 1 & 5 & -1 & -1 & 0 & 0 & 0 \\ -3 & 1 & 2 & -1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\text{round}\left(\frac{-415.38}{16}\right) = \text{round}(-25.96) = -26$$

$$Q = \begin{bmatrix} 16 & 11 & 10 & 16 & 24 & 40 & 51 & 61 \\ 12 & 12 & 14 & 19 & 26 & 58 & 60 & 55 \\ 14 & 13 & 16 & 24 & 40 & 57 & 69 & 56 \\ 14 & 17 & 22 & 29 & 51 & 87 & 80 & 62 \\ 18 & 22 & 37 & 56 & 68 & 109 & 103 & 77 \\ 24 & 35 & 55 & 64 & 81 & 104 & 113 & 92 \\ 49 & 64 & 78 & 87 & 103 & 121 & 120 & 101 \\ 72 & 92 & 95 & 98 & 112 & 100 & 103 & 99 \end{bmatrix}$$

# JPEG quantization

- Quality in per cent (%) from 0 to 100 with according predefined quantization matrices
- Custom quantization matrices possible
- Separate quantization matrices for luma and chroma (higher quantizers for chroma)
- Be aware: 100% quality is not lossless (quantization matrix for 100% quality contains many 1 values, but not only!)

# Quantization effects

Quality  
100%



Quality  
50%



Quality  
25%

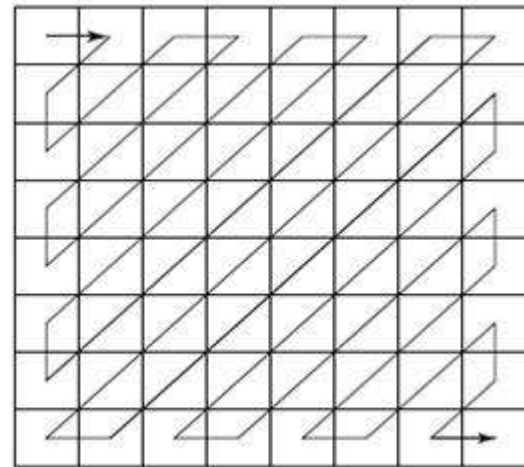


Quality  
0%



# Zigzag scan

- Subsequent zeros can be compressed more efficiently → scan matrix in an order which makes subsequent zeros more likely
- Higher frequencies are likely to be zeroed by quantization
- Zigzag scan reorders coefficients from low to high frequencies



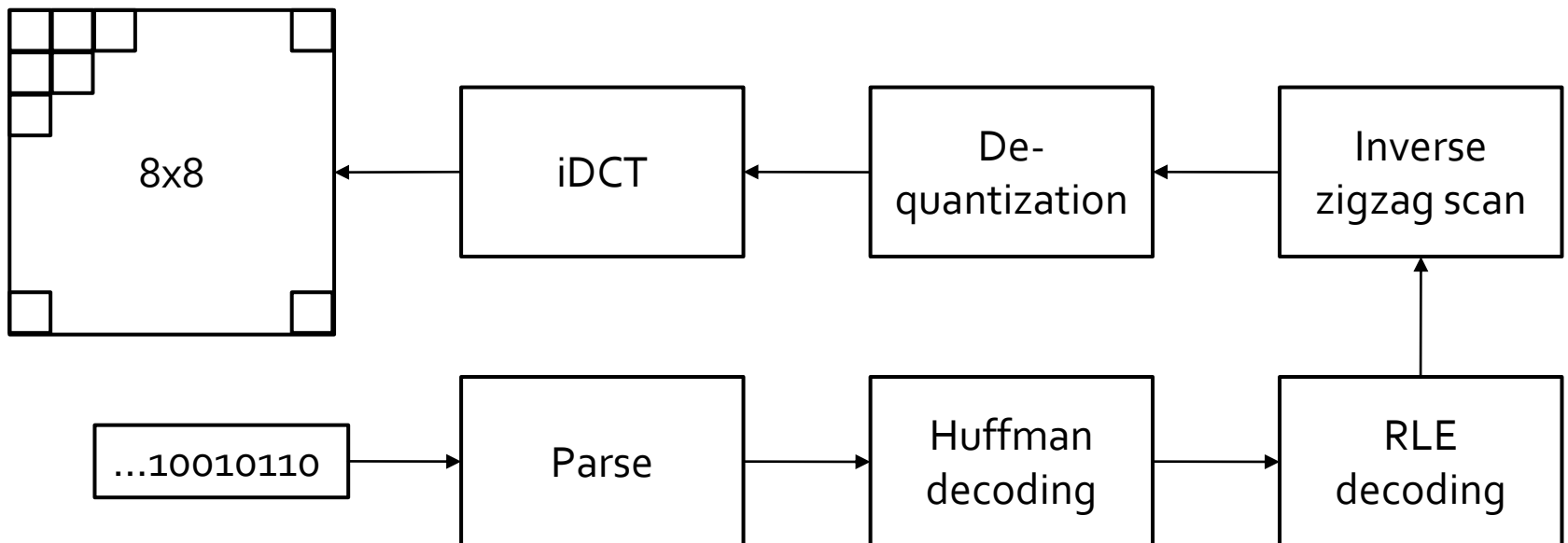


# Entropy coding

- Lossless coding of coefficients scanned in zigzag order
- Run-length encoding (RLE) for sequences of zeros with special „EOB“ marker at the end to indicate that the rest of the coefficients is zero
- Huffman coding for actual coefficient differences based on their probability
- Custom Huffman tables possible

# JPEG decoding

- Inverse encoding process
- Dequantization is lossless; loss of data occurred in quantization process during encoding
- Zero coefficients remain zero → artifacts



# Compression artifacts I

- Blocking (macroblocks are encoded separately  
→ edges don't fit together smoothly)
- Blurring (loss of too many high frequencies)



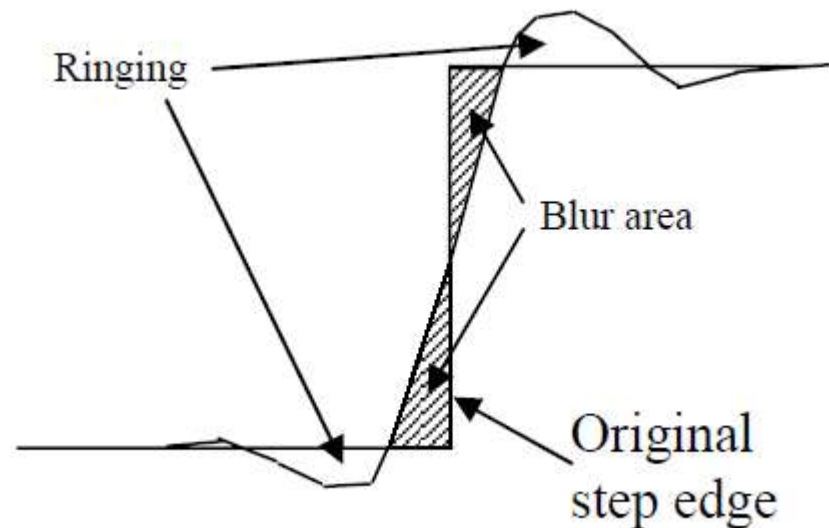
Blocking



Blurring

# Compression artifacts II

- Ringing (edges cannot be accurately represented by „continuous“ base functions)
- Over- and undershooting („minus“ red is cyan)



# Compression artifacts III

- Basis function artifacts (very high quantization makes single basis functions visible)
- Stair case artifacts (diagonal edges cannot be represented accurately by horizontal and vertical base functions)



# Quality measurement

- Different methods for objective and subjective quality measurement
- Subjective measurement using humans who rate the video quality on a defined scale (costly and time consuming)
- Objective measurement using mathematical formulas can only approximate subjective measurements but is less time consuming

# Objective quality metrics

- Measure difference between original image/video and its encoded/decoded version
- Sum of absolute differences (SAD)
- Sum of absolute total differences (SATD)
- Sum of squared differences (SSD)
- Mean squared error (MSE)
- (Y-)PSNR derived from MSE (logarithmic)
- More metrics

# MSE and PSNR

- MSE for m times n samples for original samples I and coded samples K

$$MSE = \frac{1}{m \cdot n} \sum_{i=0}^{m-1} \sum_{j=0}^{n-1} [I(i, j) - K(i, j)]^2$$

- Y-PSNR (luma only),  $MAX_I = 2^8 - 1$  for 8 bit samples

$$PSNR = 10 \cdot \log_{10} \left( \frac{MAX_I^2}{MSE} \right) = 20 \cdot \log_{10} \left( \frac{MAX_I}{\sqrt{MSE}} \right)$$

- PSNR calculation for color pictures

# PSNR value examples

- Theoretically values between 0 and inf. dB
- Typical range: 25dB to 40dB
- 20dB or less usually indicate severe distortion



QP: 50 | PSNR: 20,45dB

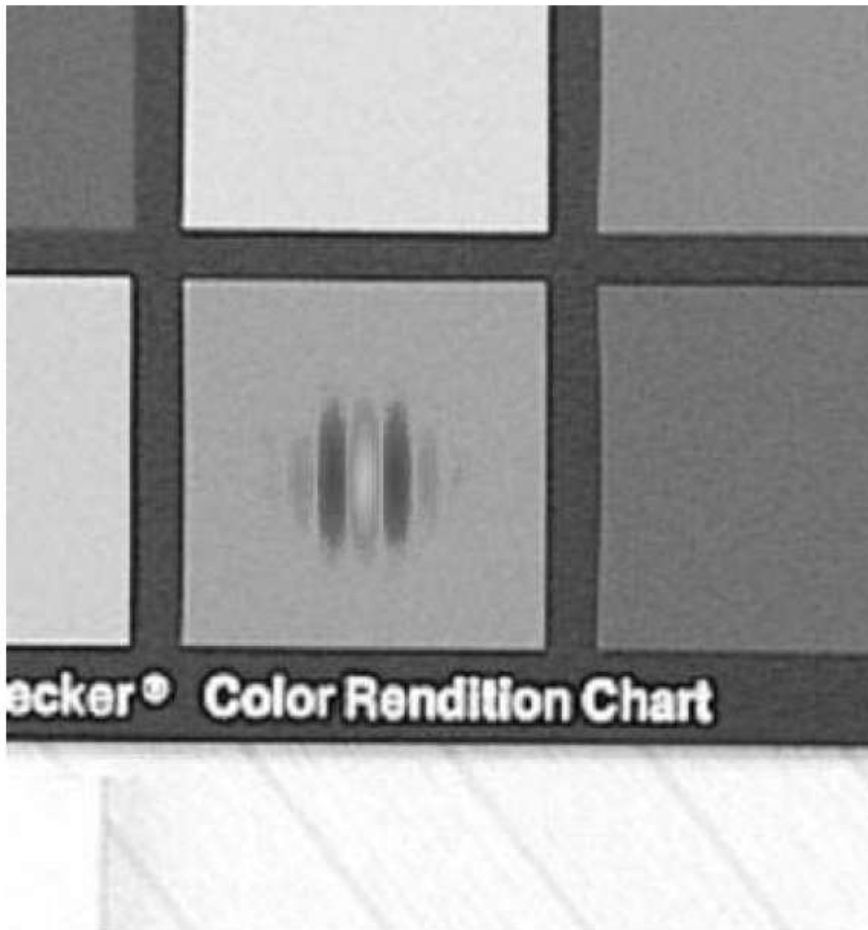


QP: 30 | PSNR: 31,88dB



QP: 10 | PSNR: 45,63dB

# One problem with objective metrics



Both coded pictures have about the same MSE. Can you see why?

# Structural similarity (SSIM)

- Approximate subjective quality measurement by measuring structural similarity of image blocks (typically 8x8 samples)
- Take contrast, blurriness and other parameters into consideration (similar to human eye)
- More complex to calculate than Y-PSNR, but also higher correlation with subjective quality measurements (typical trade-off)

# Y-PSNR/SSIM example I



Y-PSNR: 32,08dB  
SSIM: 0,865



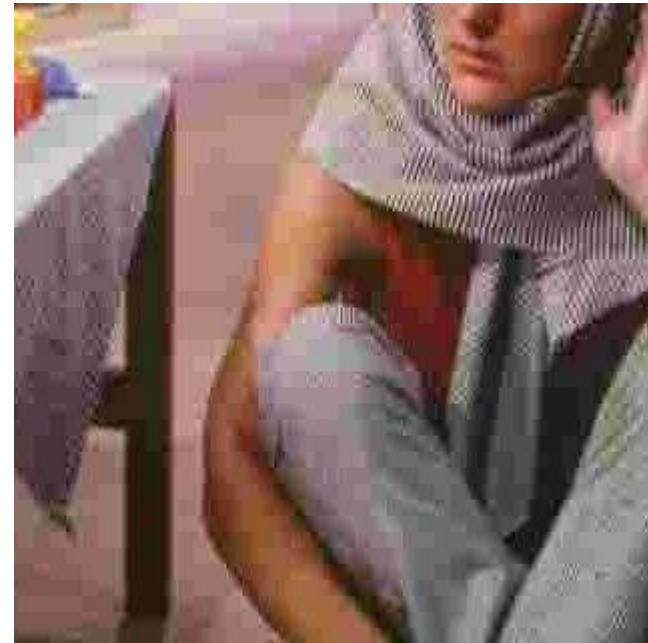
Y-PSNR: 35,50dB  
SSIM: 0,921

Y-PSNR range: 0 to inf. dB (best)  
SSIM: -1 to 1 (best)

# Y-PSNR/SSIM example II



Y-PSNR: 30,81dB  
SSIM: 0,866



Y-PSNR: 29,12dB  
SSIM: 0,822

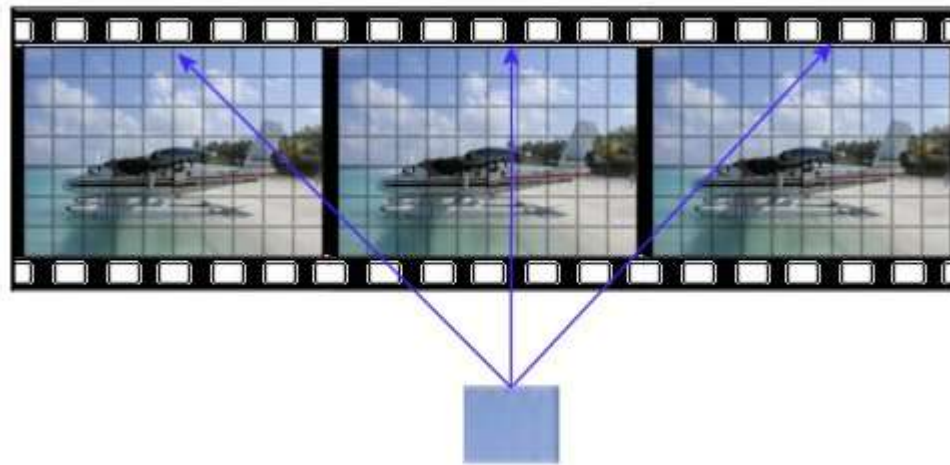
Y-PSNR range: 0 to inf. dB (best)  
SSIM: -1 to 1 (best)

# Video coding

- Videos („motion pictures“) are sequences of images with high temporal correlation
- Video coding uses image coding techniques and makes use of this temporal correlation
- Motion is perceived at ca. 20 pictures per second, fluid perception requires a higher frame rate (depends on content, individual, and lightning conditions)

# Temporal correlation

- Pictures are similar to one another
- Exploit this property by coding differences between pictures instead of the pictures

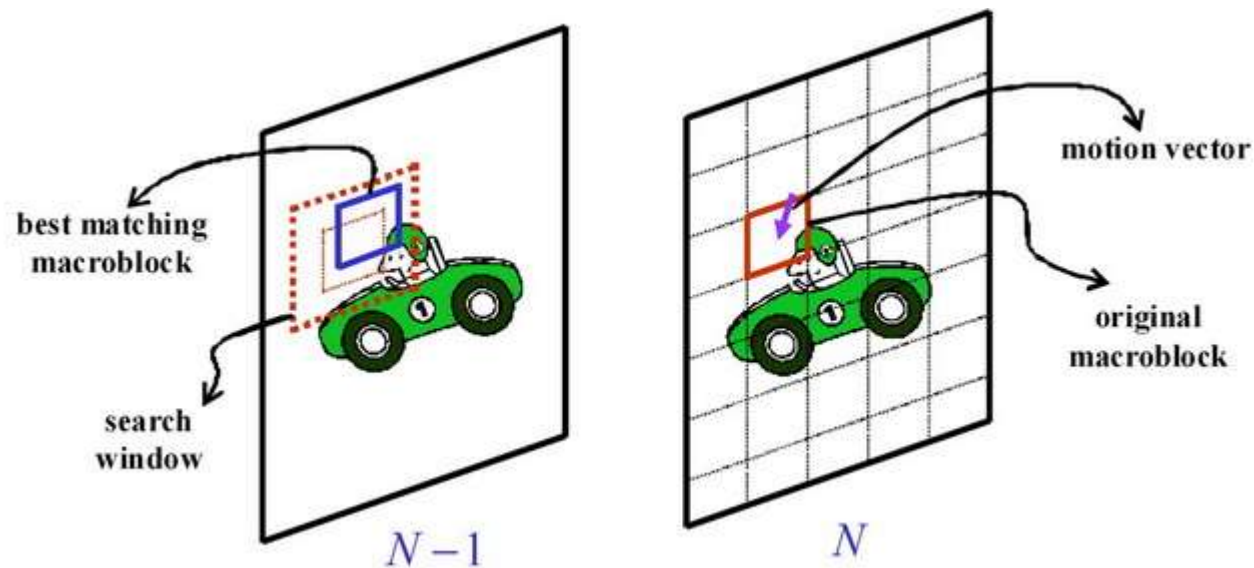


# Pictures and picture types

- Pictures (frames) can be of different types
  - I (Intra) pictures/frames: Fully coded similar to JPEG algorithms described earlier ("key" frames, relevant for scene changes and fast forwarding)
  - P (Predicted) pictures/frames: Only differences to previous pictures/frames are coded (use of temporal correlation between pictures)
  - More picture types to be described later

# Motion estimation

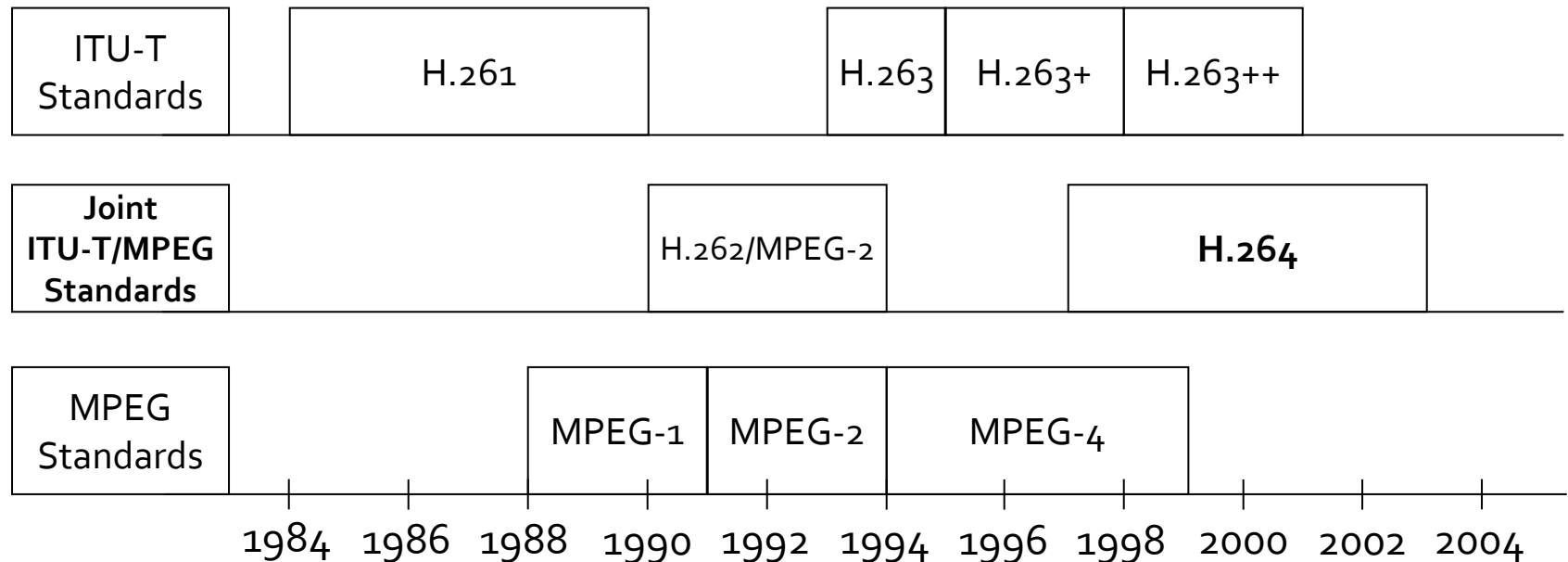
- Used in P pictures to find similar macroblocks in previously coded pictures
- Motion estimation: find best match



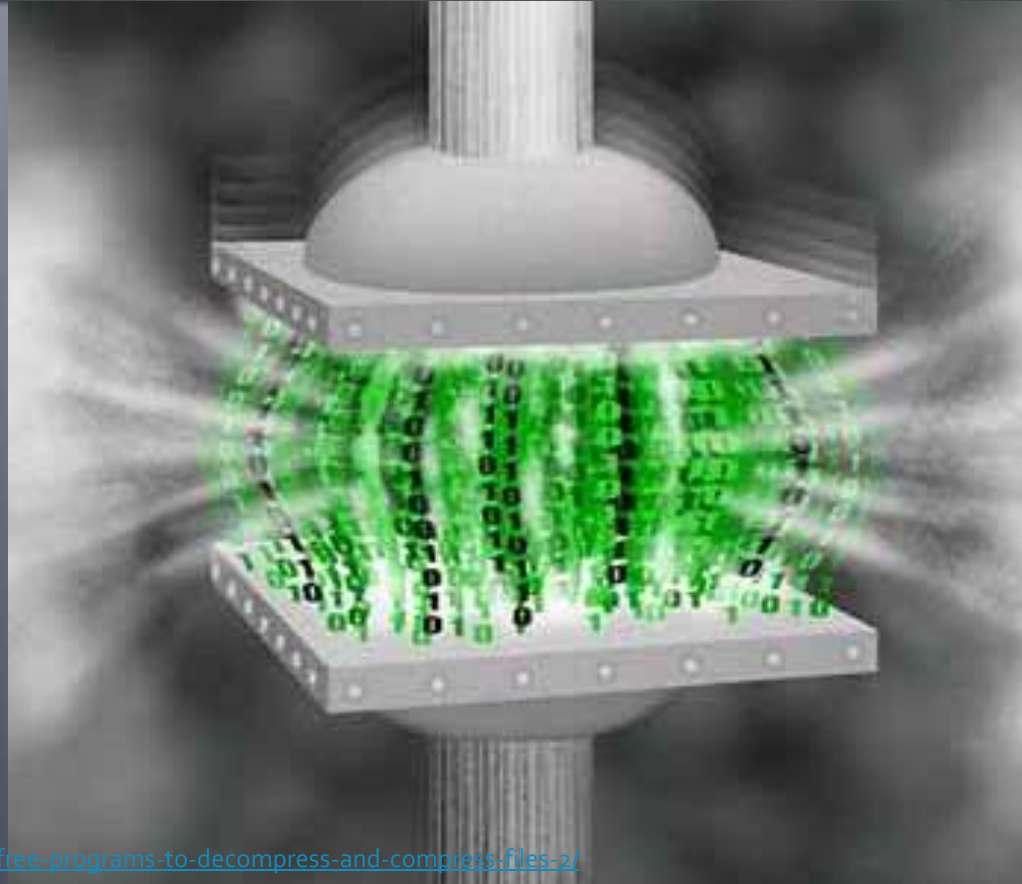
# Motion coding and decoding

- Calculate difference between macroblock match and current macroblock
- Difference is treated like a regular macroblock (transform, quantization etc.)
- To be saved additionally: motion vector and match picture “number” (or distance)
- Reconstruction by applying difference to reference macroblock in decoder

# Video coding standards time line

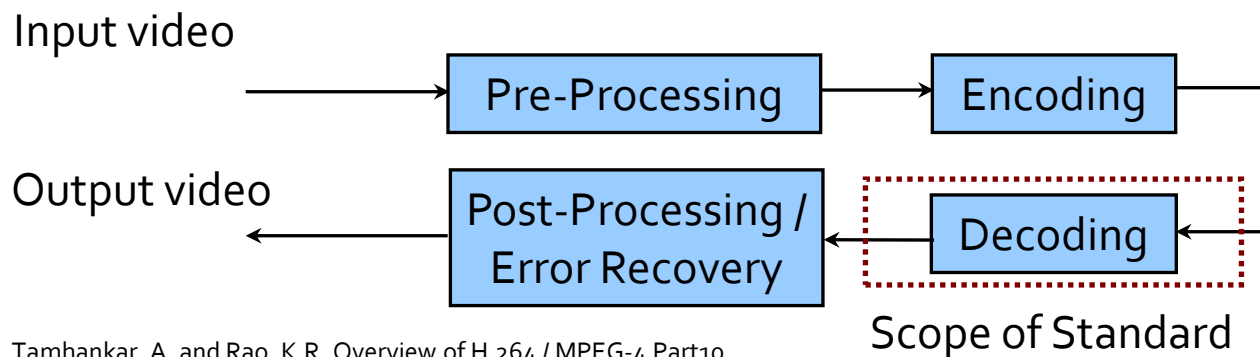


# The H.264 standard

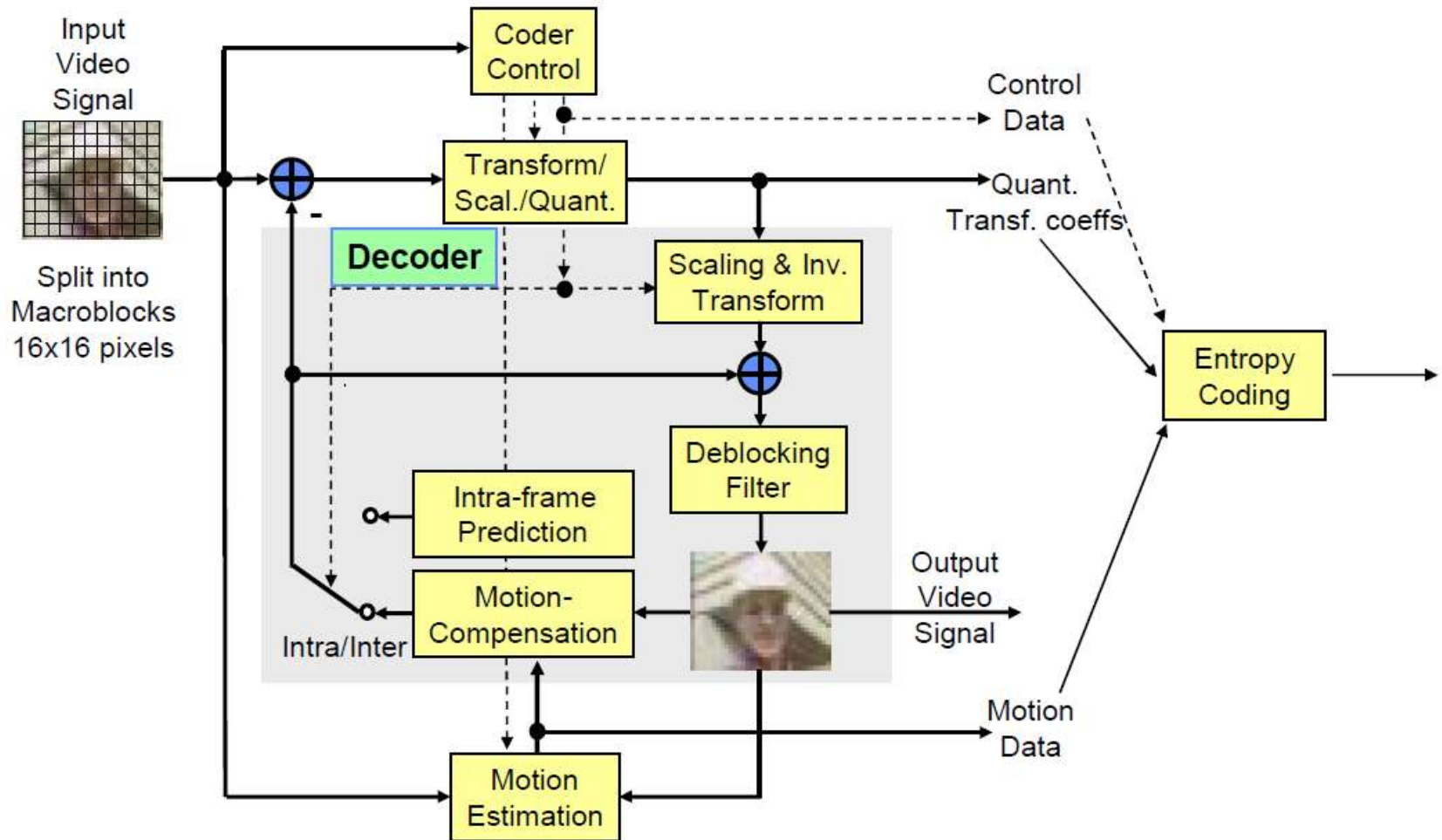


# H.264

- State-of-the-art video (de)coding standard
- Only specifies how decoding is to be done
  - Encoder design can be arbitrary as long as the syntax of the generated bit stream is valid
  - No guarantee for a specific quality as encoder decisions are not specified

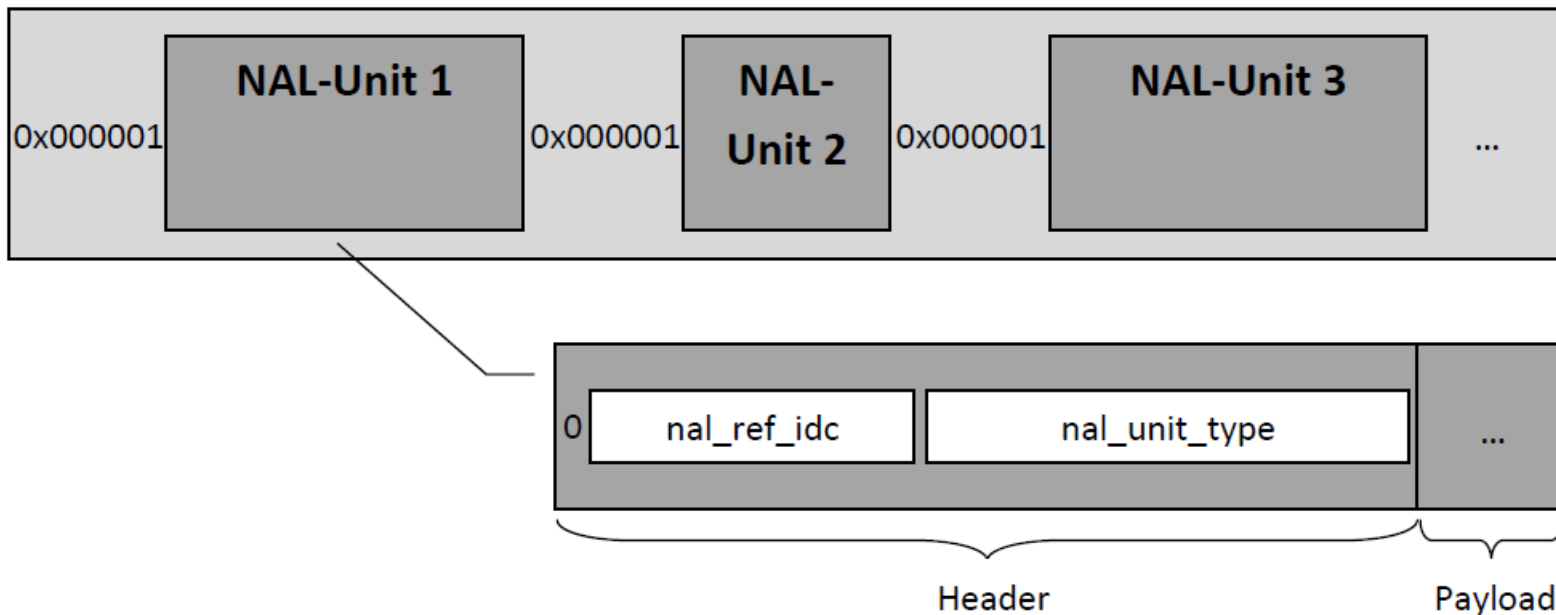


# H.264 coding structure



# NAL units (NALUs)

- Store pictures (or parts of them)
- Allow for easy transmission over networks (one NALU per package)



# Differences to JPEG compression

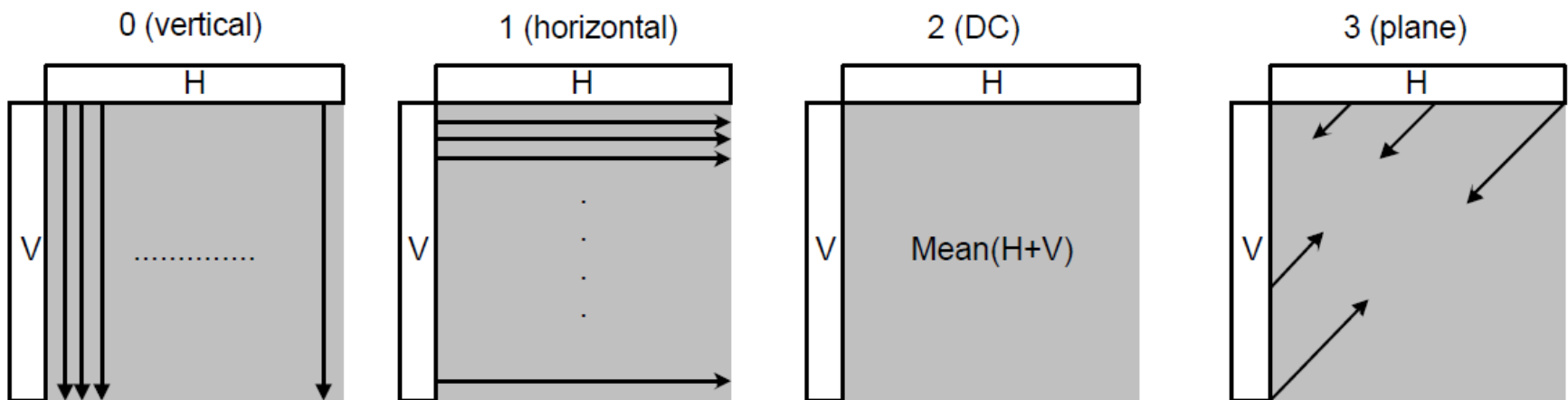
- 16x16 macroblocks instead of 8x8 blocks
- 16 4x4 blocks per macroblock which are transformed separately
- Integer transform (similar to DCT) to avoid floating point rounding errors and allow for better performance
- Different scanning order
- Additional filtering
- More efficient entropy coding

# Intra prediction

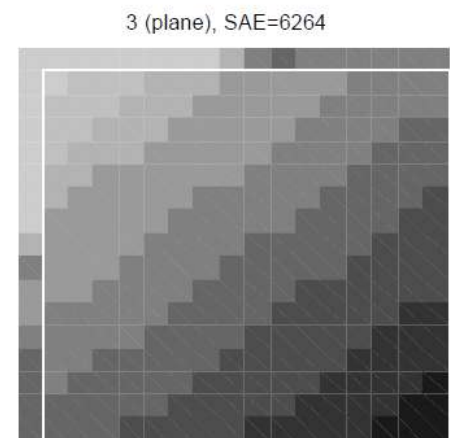
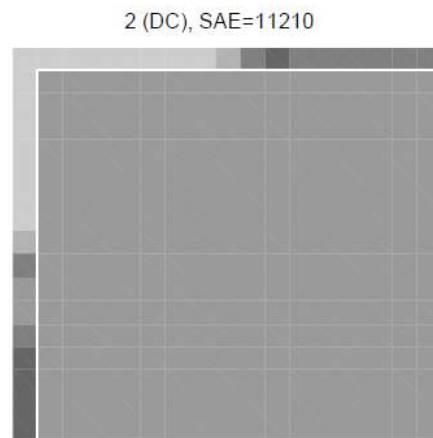
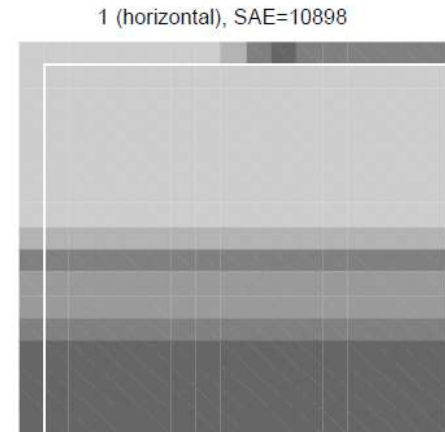
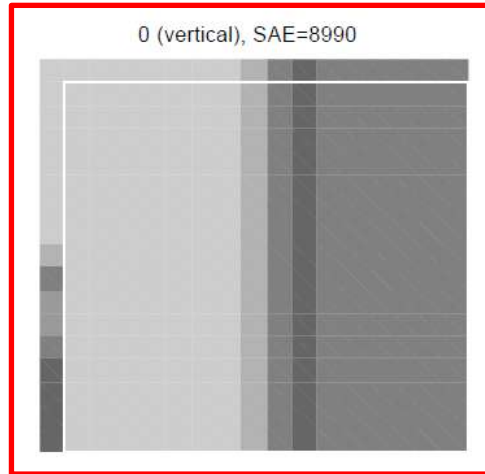
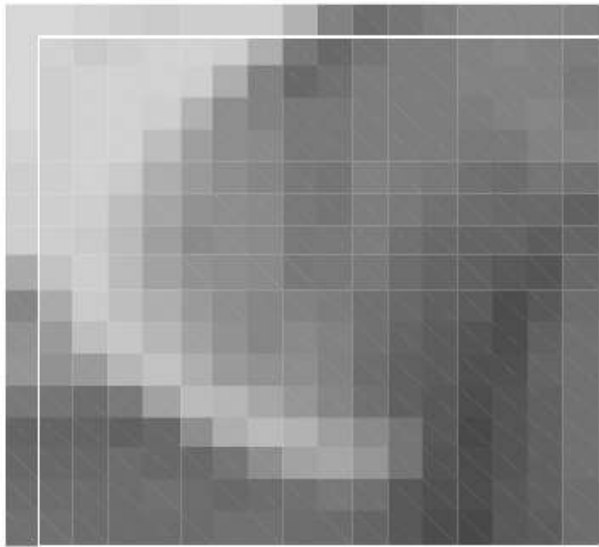
- Intra coded macroblocks are not fully coded, but predicted from their neighbours (use of spatial correlation within picture)
- Either  $4 \times 4$  or  $16 \times 16$  block prediction possible
- Blocks at picture borders are also predicted
- Intra coded macroblocks can also appear in P pictures if no appropriate match is found during motion estimation

# 16x16 intra prediction modes

- Encoder can choose between single 16x16 intra prediction or 16 separate 4x4 predictions
- Less signalling bits for 16x16 modes required
- 4 possible 16x16 modes, 9 4x4 modes

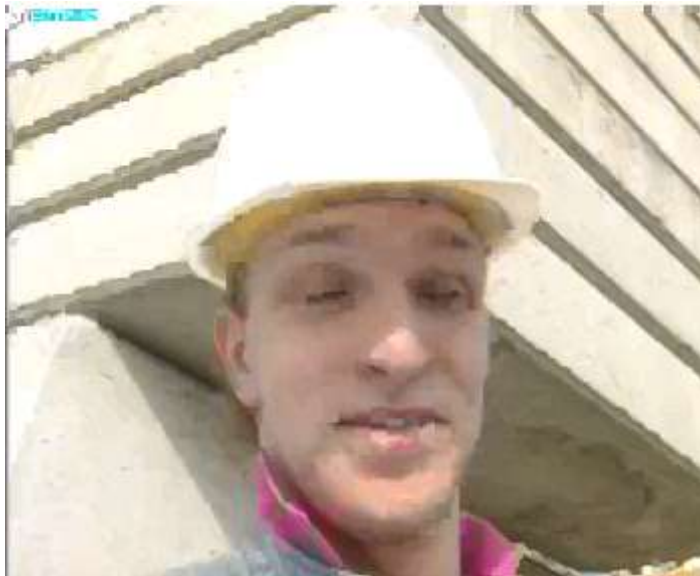


# 16x16 intra prediction example



# Intra prediction efficiency

- Prediction vs. final picture



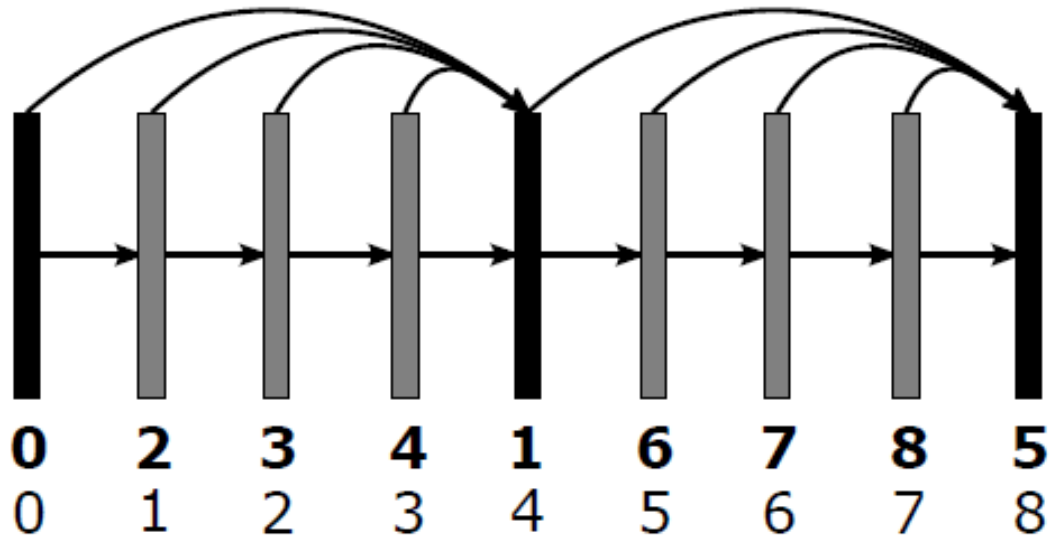
- 16x16 modes in helmet area, rest: 4x4 modes

# B pictures

- Bidirectional prediction also allows prediction based on “future” frames
- Allow references to past or to “future” pictures, depending on what costs less bits
- Coding order has to be adapted as real “future” prediction is not possible
- Coding order and display order differ if B pictures are used

# Coding order vs. display order I

- H.264 allows coding order to differ arbitrarily from display order
- References have to be coded first



# Inter prediction

- Recall: motion estimation and compensation
- Sophisticated partitioning of picture
- Use of multiple reference pictures
- Sophisticated management of reference pictures
- Recall: picture types I, P and B

# IDR pictures

- “Instantaneous Decoding Refresh”
- Coded like I pictures, but in special NAL unit
- Difference to I pictures: prediction border (no references allowed to frames before IDR)
- Used as resynchronisation points
  - At the beginning of a video stream
  - Fast forward
  - After package loss

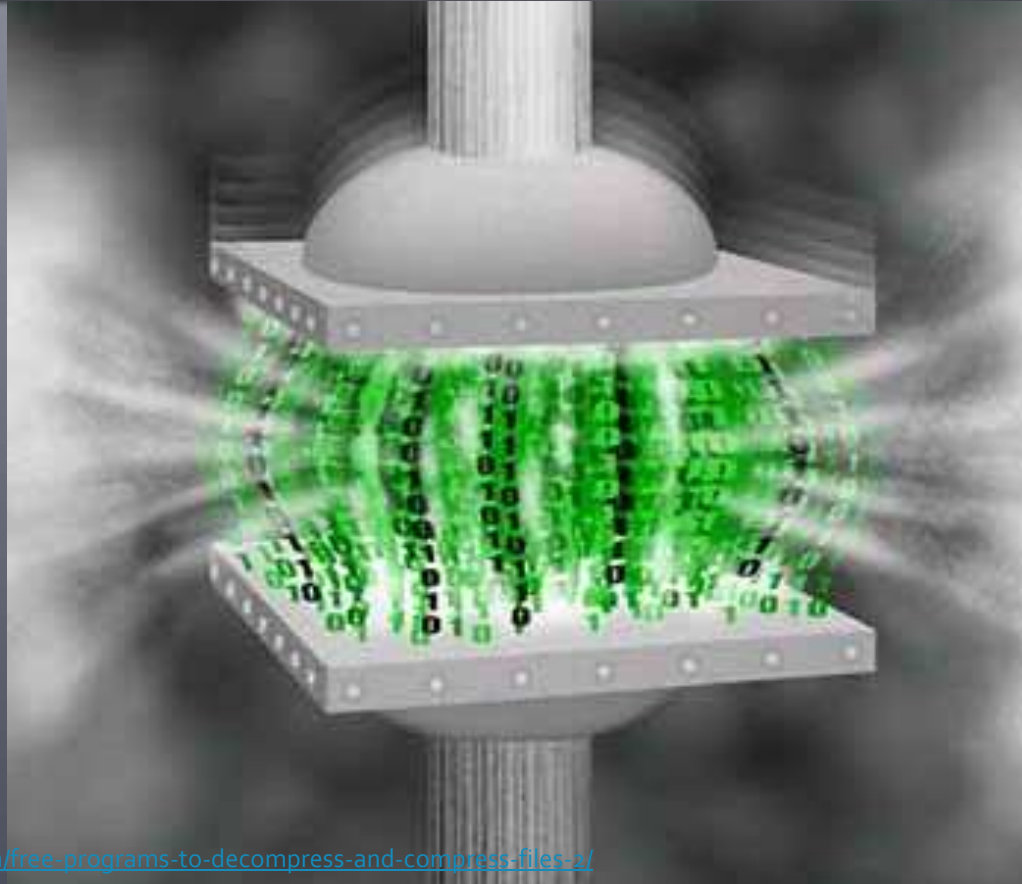
# H.264 implementations

- Large number of commercial encoders and decoders, few free implementations
- Both encoder and decoder are very complex
- Decoders are equal in quality (at least in theory) as the standard defines how decoding has to be done → decoder speed matters
- Encoder quality and feature implementations vary as the encoder design can be arbitrary

# Popular implementations

- Decoders
  - ffmpeg (open source)
  - CoreCodec CoreAVC (commercial)
- Encoders
  - x264 (open source)
- Codecs (encoders and decoders combined)
  - MainConcept (commercial)
  - DivX H.264 (free and commercial version available)
  - Nero Digital (commercial)

# Real-time aspects of H.264 video coding

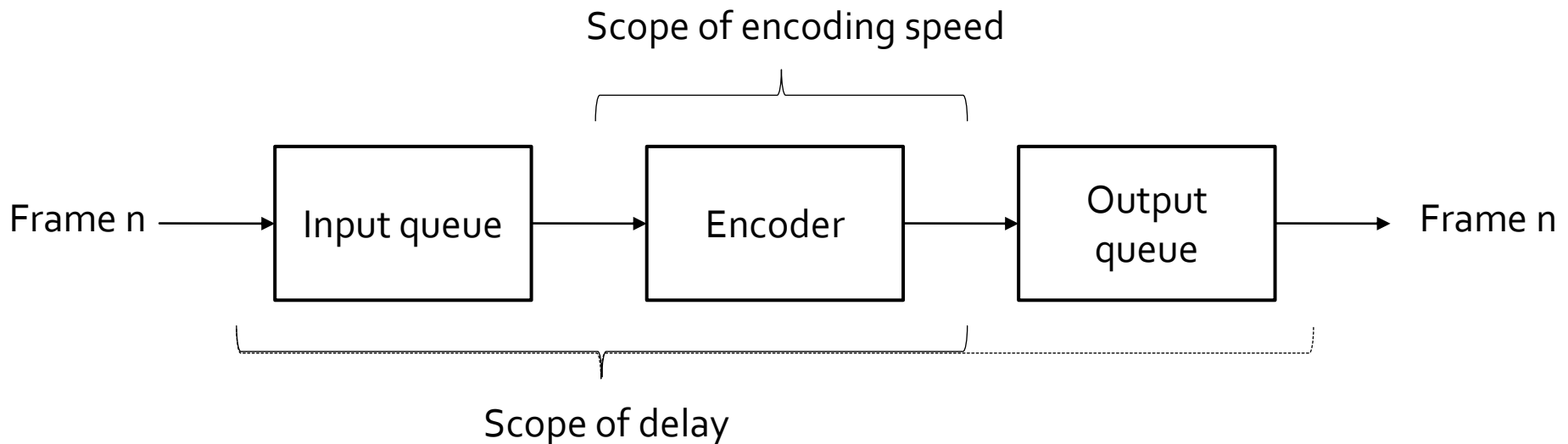


# Definition of real-time

- Video coding concept of real-time is different than in classical real-time systems with soft or hard deadlines
- Frame (processing) rate of encoder has to be greater than or equal to frame rate of video in time average (in theory!)
- Delay issues have to be coped with separately

# Encoding speed and delay

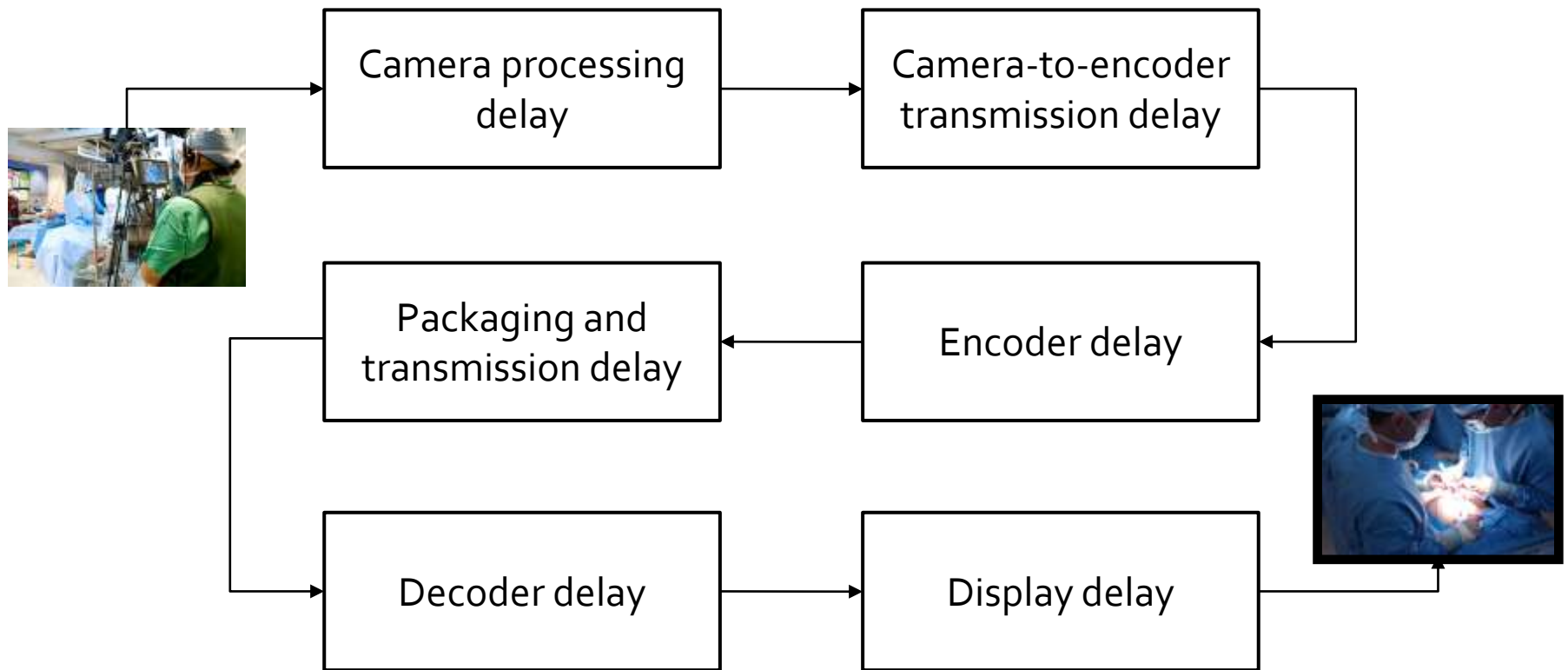
- Encoding speed is frame processing rate of encoder only (also depends on input)
- Delay includes queues and more (ambiguous)



# Delay

- Multiple definitions
  - Encoding delay (duration of pure frame encoding)
  - Encoder delay (duration from frame input to output by encoder; greater than or equal to encoding delay – beware of reordering!)
  - End-to-end delay (duration between recording and display for live streams; should be minimal)
- Definition of delay depends on application
- Telemedicine applications require low delay

# Live end-to-end delay sources



# Delay example I

- Example: 25 fps recording (40ms per frame)
- Average recording delay for one frame: 20ms
- Average encoder delay also ca. 20ms (jitter)
- Transmission depends on channel and buffers:  
>40ms (longer for TCP/IP and similar channels)
- Decoder has to decode whole picture: average delay of 20ms (jitter due to different frames)
- 50 Hz display adds another min. 10ms delay

# Delay example II

- Total delay depends on various sources
- At 25fps, the minimum delay is at least 100ms (nearly 3 whole frames)
- Frame rate has significant impact (increasing the frame rate lowers the delay)
- Some sources of delay cannot be minimized
- Some can, but require additional efforts (extra hardware/software/money etc.)

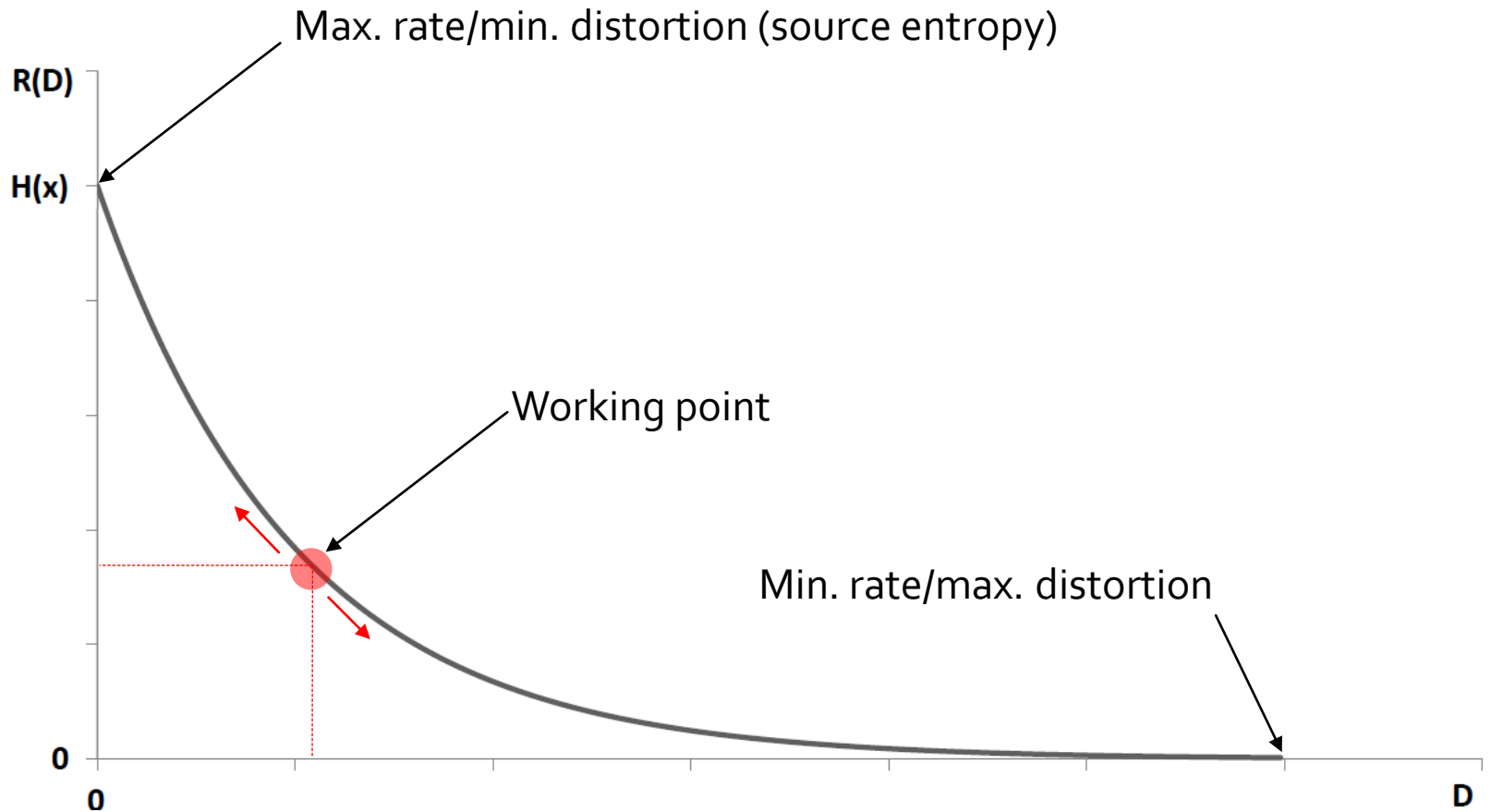
# How to lower end-to-end delay

- Lower delay of each delay source
- Focus on main sources of delay
  - Transmission (faster connections, prioritized package handling etc.)
  - Encoding (faster encoder, different parameters)
- Decoding complexity is influenced by encoder and its parameters (“ultra low delay” (ULD) encoders/decoders help)
- Transmission delay is a network layer issue

# Rate-distortion optimization (RDO)

- Video coding is always a trade-off between quality and bit rate
- Quality is “inverse” distortion
- Quality goal: best quality at given bit rate
- Bit rate goal: lowest bit rate at given quality
- Rate distortion optimization: achieve goals
- Base encoder decisions on RDO

# Rate distortion curve



# Effect of coding tools/parameters

- RDO requires to “try” each mode (affects time)
- Higher resolution of input video entails more encoding operations (affect time)
- B pictures require picture reordering (affects delay); combined with RDO there are yet more modes to test (affect time)
- Search range and number of pictures for motion estimation prolong search (affect time)

# Practical parameters example

- x264 (open source H.264 encoder) uses presets to specify coding speed vs. compression efficiency trade-off
- --preset parameter allows “ultrafast” to “veryslow” (and even “placebo”)
- Default settings: 3 B pictures, 3 reference pictures for motion estimation with a range of 16x16 each (and some more restrictions)

# Practical parameters example I

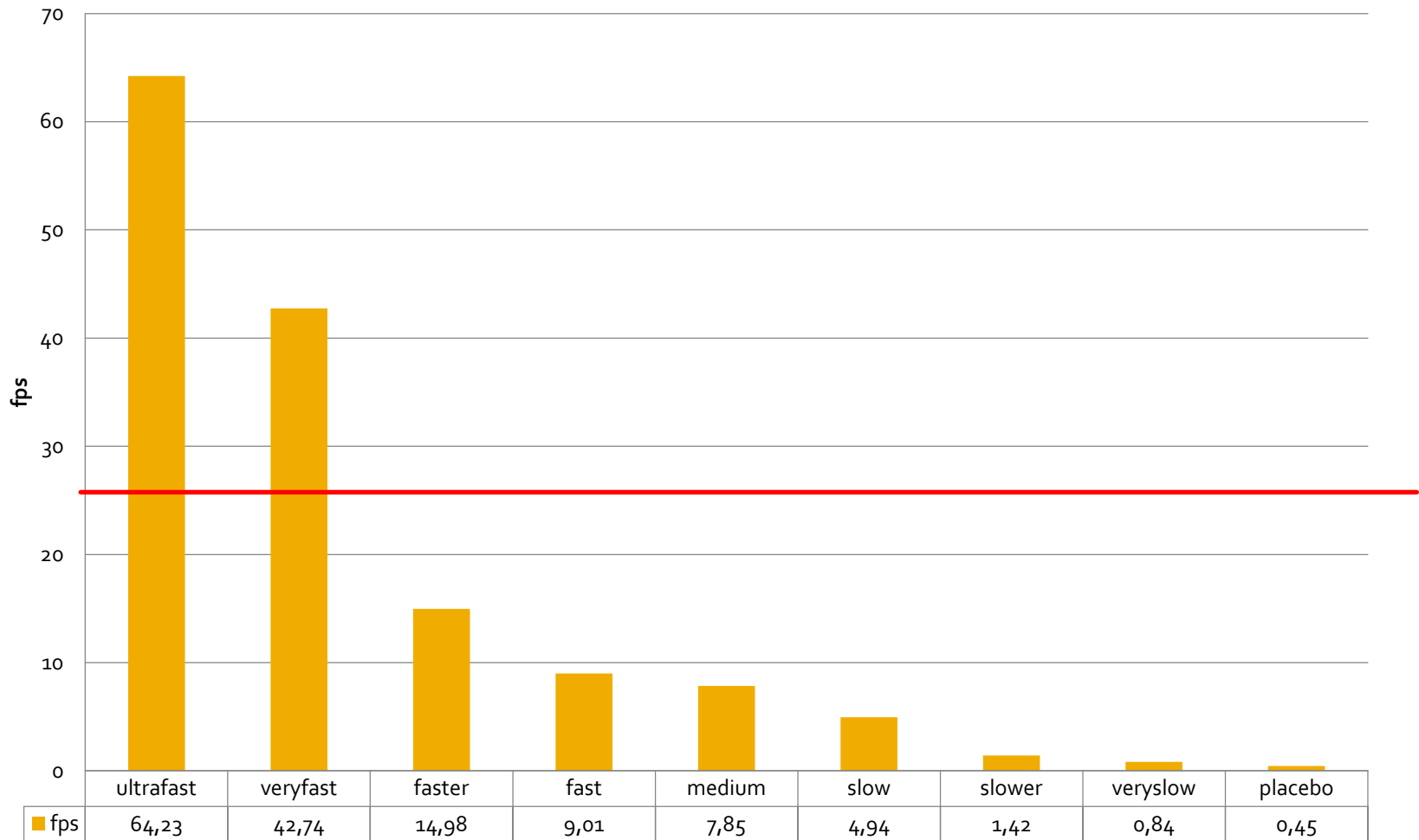
- Important “ultrafast” parameter changes:
  - No B pictures
  - 1 reference picture for motion estimation
  - Full pixel diamond motion estimation (very fast)

# Practical parameters example II

- Important “veryslow” parameter changes:
  - 8 B pictures with adaptive B picture decision
  - 16 reference pictures (maximum allowed)
  - ME range  $24 \times 24$
  - RDO for all modes and picture types
  - Psychovisual optimizations (e.g. Trellis quantization)
  - Psychovisual RDO

# x264 preset speed comparison

Intel Core 2 Quad Q6600 **720p** encoding speed



# Encoder speed comparison (MSU)

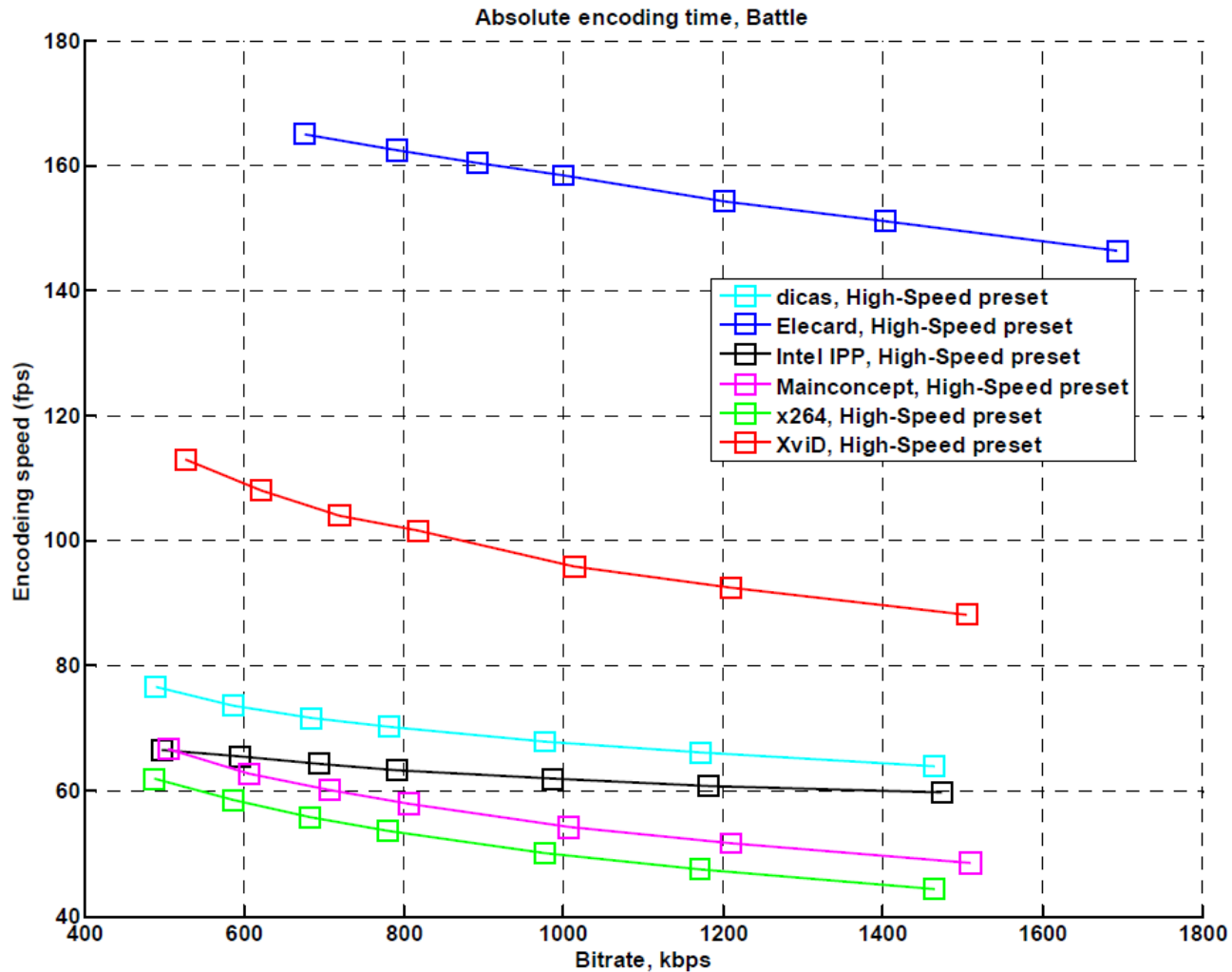
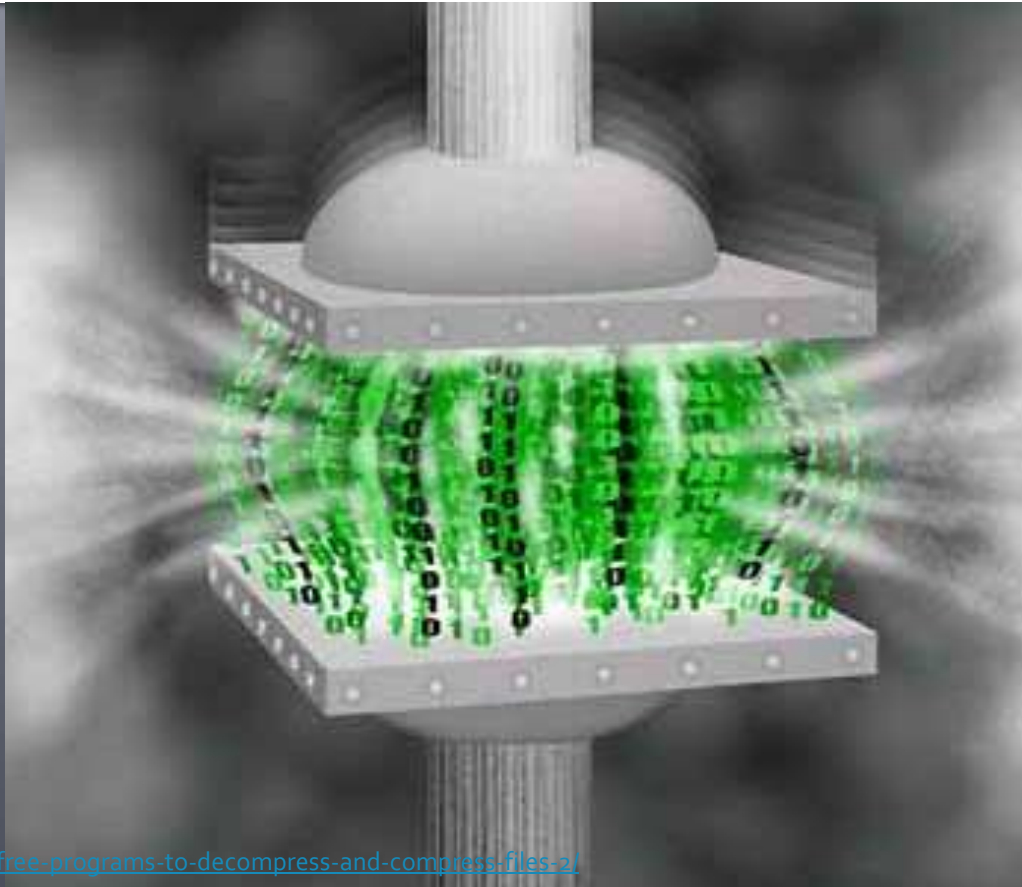


Image source: CS MSU Graphics & Media Lab Video Group: MPEG-4 AVC/H.264 Video Codecs Comparison.

[http://compression.ru/video/codec\\_comparison/pdf/msu\\_mpeg\\_4\\_avc\\_h264\\_codec\\_comparison\\_2009.pdf](http://compression.ru/video/codec_comparison/pdf/msu_mpeg_4_avc_h264_codec_comparison_2009.pdf) (14.11.2010), 2009.

# H.264 error resilience tools



# Bit errors in video coding

- Bit errors can cause corrupt macroblocks or macroblock groups during decoding
- Errors can propagate throughout the picture through intra prediction
- Errors can propagate to the next/previous pictures through inter prediction
- Prediction mechanisms favor propagation
- Error resilience tools minimize errors, but cost extra bits (less efficient compression)

# Small burst error effects example



Image source: Boulos, F., Wei Chen; Parrein, B.; Le Callet, P.: A new H.264/AVC error resilience model based on Regions of Interest. 17th International Packet Video Workshop, 2009, pp.1-9, 2009

# Large burst error effects example



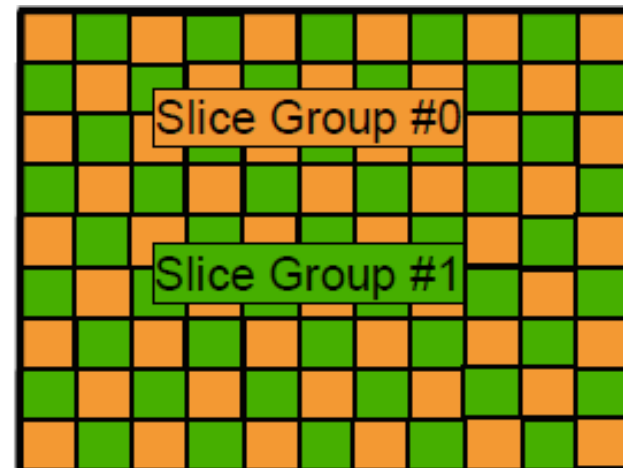
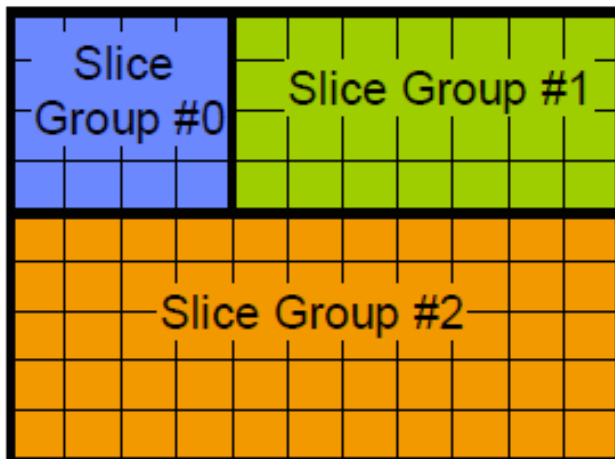
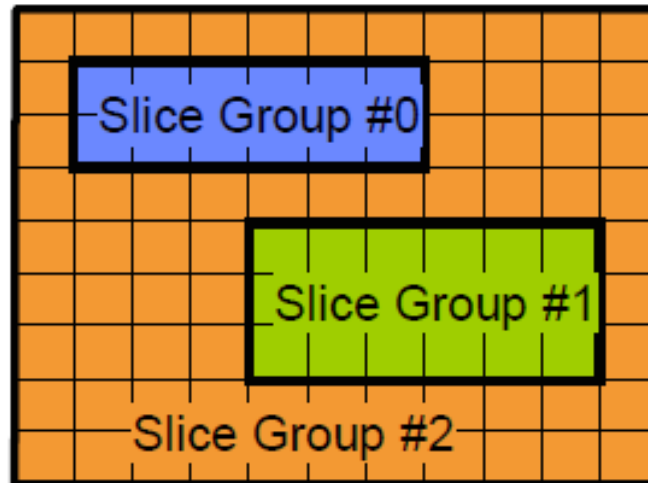
# Tool: Data partitioning

- Slice data (encoded macroblocks) is split into three data partitions: A, B and C
- Partition A: slice header and macroblock header information (coding mode etc.)
- Partition B: macroblock data for intra blocks
- Partition C: macroblock data for inter blocks
- Each partition is encapsulated in a separate NAL unit → prioritization of A over B/C possible

# Slices

- Separation of picture into separate independent parts (slices)
- No prediction between slices allowed → independency
- Slice types within a picture can differ (I, P, B)
- Slices can be grouped into slice groups

# Slices and slice groups



# Tool: Redundant slices

- Possibility to code macroblocks more than one time and send them as additional, but redundant slice (lower quality possible)
- Decoder favors primary slice and discards the redundant slice if both are available
- If the primary slice is not available, the decoder uses the according redundant slice (if available) → reconstruction possible

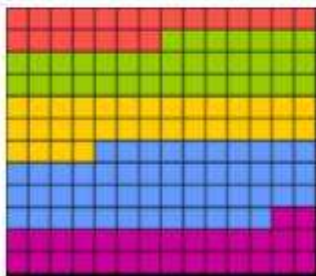
# Tool: Flexible macroblock ordering

- Defines fine-grain macroblock association with slice groups
- Different scanning patterns possible
- Dispersing macroblocks reduces sensitivity to burst noise on transmission channel
- Both implicit and explicit assignment to slice groups possible through multiple map types

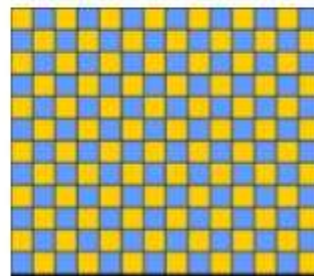
# FMO map types I

- 7 FMO map types for different use cases
- Type 0: run length based (macroblocks)
- Type 1: dispersed (p.e. checkerboard)
- Type 2: rectangular regions of interest

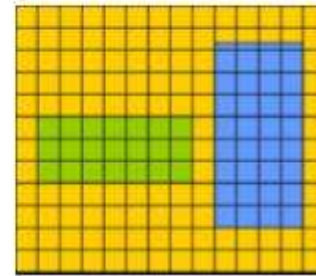
• Type 0



• Type 1



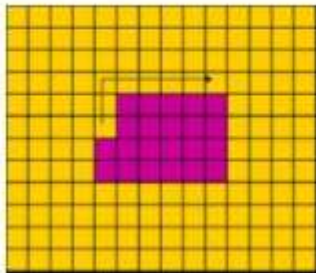
• Type 2



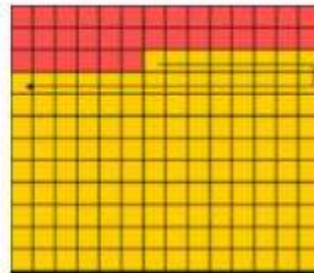
# FMO map types II

- Types 3-5: slice groups grow and/or shrink over time (growth/shrink rate specified)
- Type 6 allows arbitrary (explicit) grouping
- Arbitrary slice ordering (ASO)

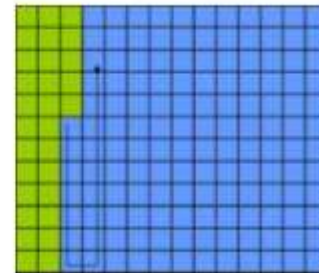
• Type 3



• Type 4



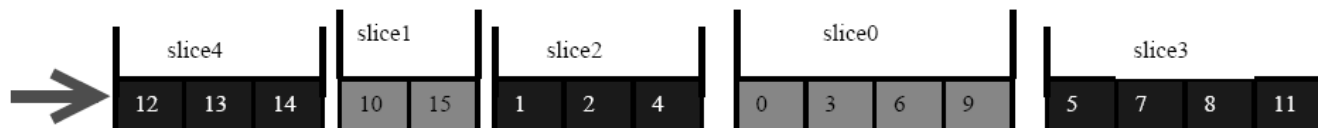
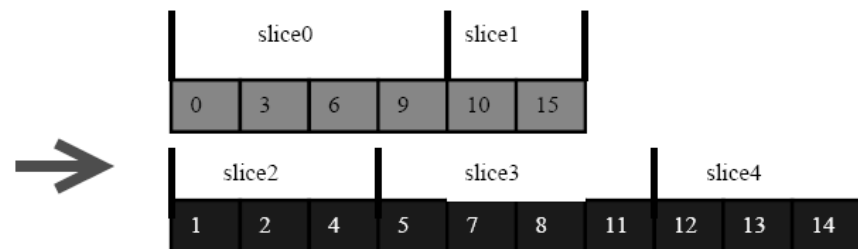
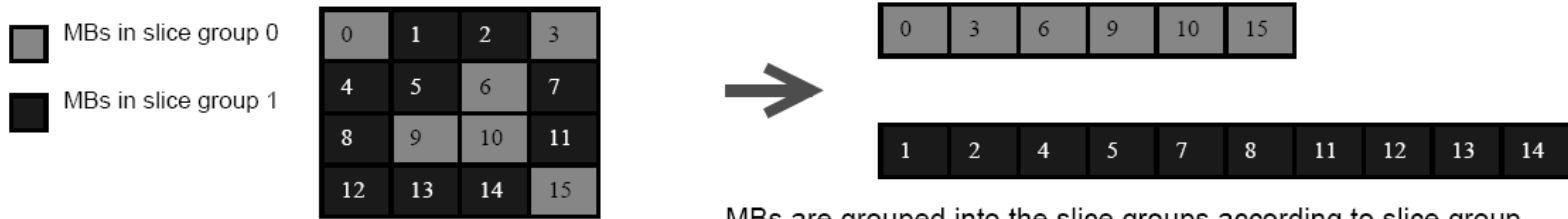
• Type 5



# Tool: Arbitrary slice ordering

- Slices don't have to be transmitted in scanning order (arbitrary ordering possible)
- Reordering may reduce effect of burst noise as it does not effect subsequent picture regions
- Priorization of slices or slice groups possible as every slice is contained in a separate NAL unit
- Fine-grain macroblock association possible with flexible macroblock ordering (FMO)

# Arbitrary slice ordering example



Slices then can be transmitted in an arbitrary order in the bitstream

# Effect of error resilience tools

- Redundant slices require additional coding (affect time)
- ASO is theoretically time-neutral as the number of coded blocks/slices stays the same
- FMO may slow down the encoder due to cache misses due to dispersed macroblocks in slice groups (affects time)
- Decoding complexity increases (affects time)

# Error concealment

- H.264 specifies that corrupt NAL units are to be discarded (syntax errors or semantical errors can be detected, some others cannot)
- Error concealment may be applied to all areas where data is missing (optional)
- Standard proposes concealment methods
- Different methods proposed by various research groups

# Error detection

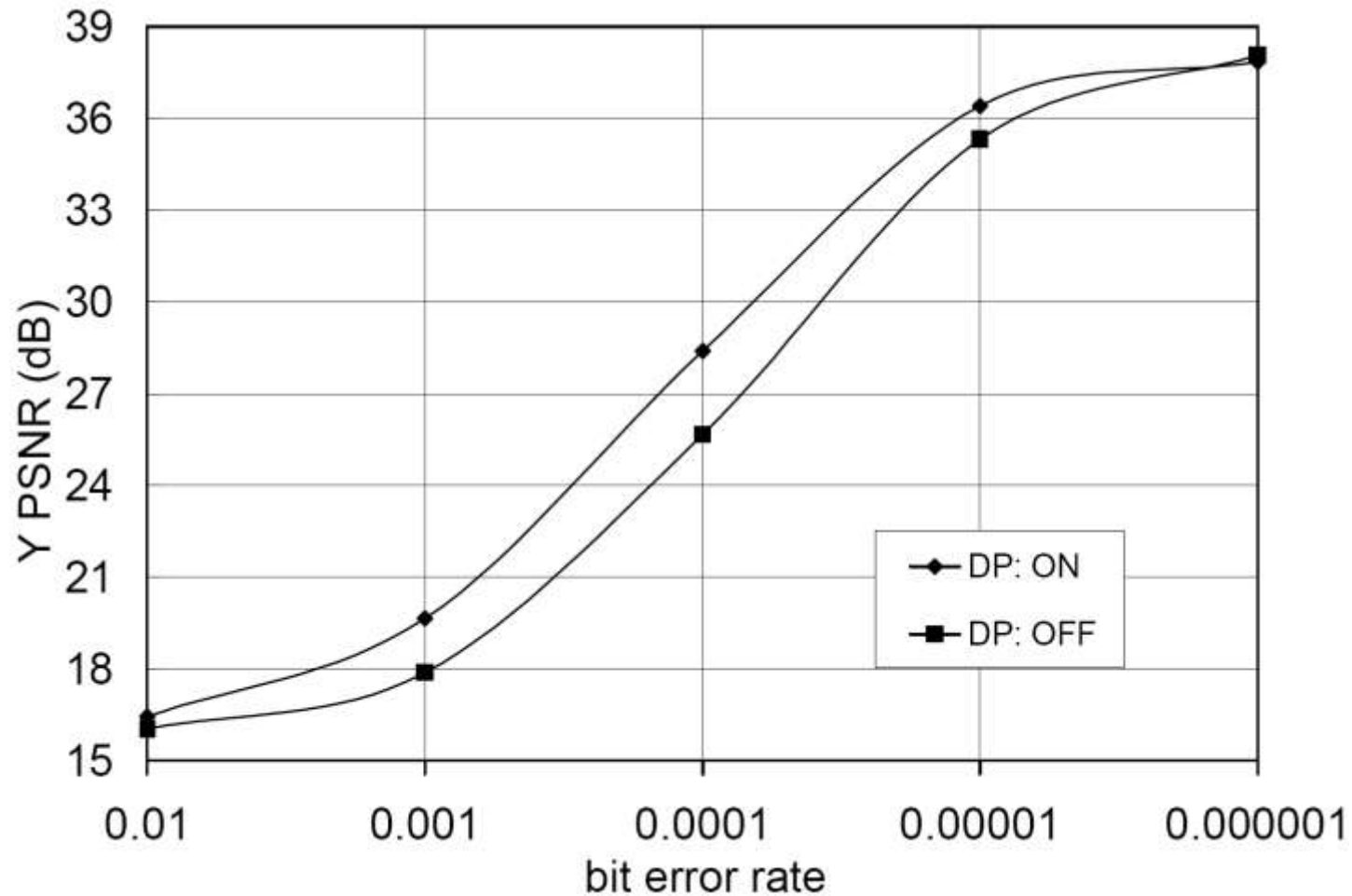
- Syntax error detection
  - Illegal values of syntax elements
  - Illegal synchronisation/header (0x000001)
  - Coded macroblock data contains more elements than specified (p.e. more than 16 in a 4x4 block)
  - Illegal entropy code (words)
- Semantics error detection
  - Out of range luma or chroma values
  - Invalid states during decoding

# Data partition loss concealment

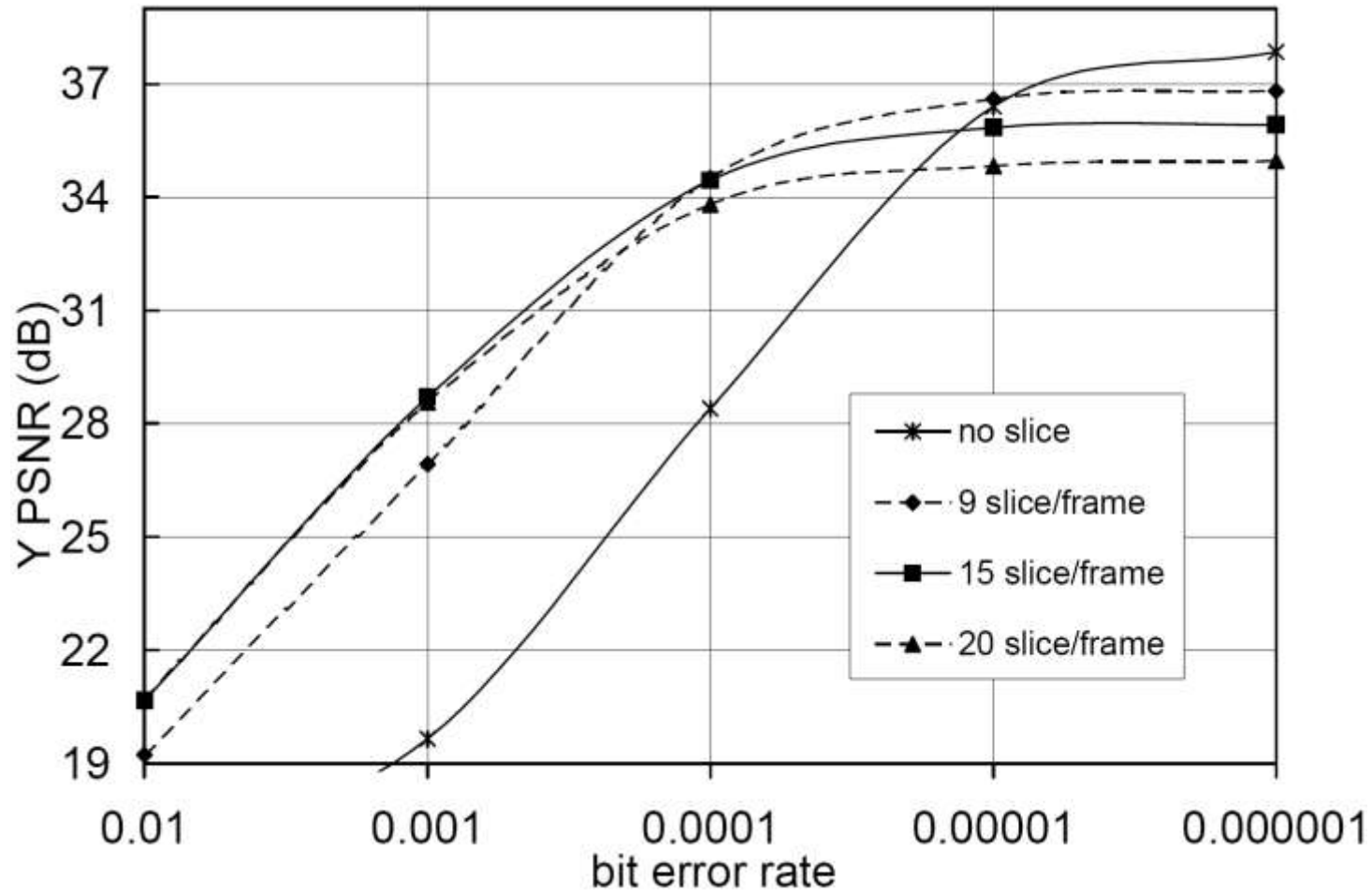
- Recall: data partitions A, B and C to prioritize information (A is the most important partition)
- Recall: B/C contain intra/inter coded data

Available Partition(s)	Concealment Method
A and B	Conceal using MVs from Partition A, and texture from Partition B; intra concealment is optional.
A and C	Conceal using MVs from Partition A and inter info from Partition C; inter texture concealment is optional.
A	Conceal using MVs from Partition A
B and/or C	Drop Partitions B and C. Use motion vectors of the spatially above MB row for each lost MB

# Data partitioning effects I



# Data partitioning effects II



# FMO effects

- Checkerboard pattern allows interpolation if one slice group gets lost or damaged
- Concealment: use previous pictures' blocks



Original



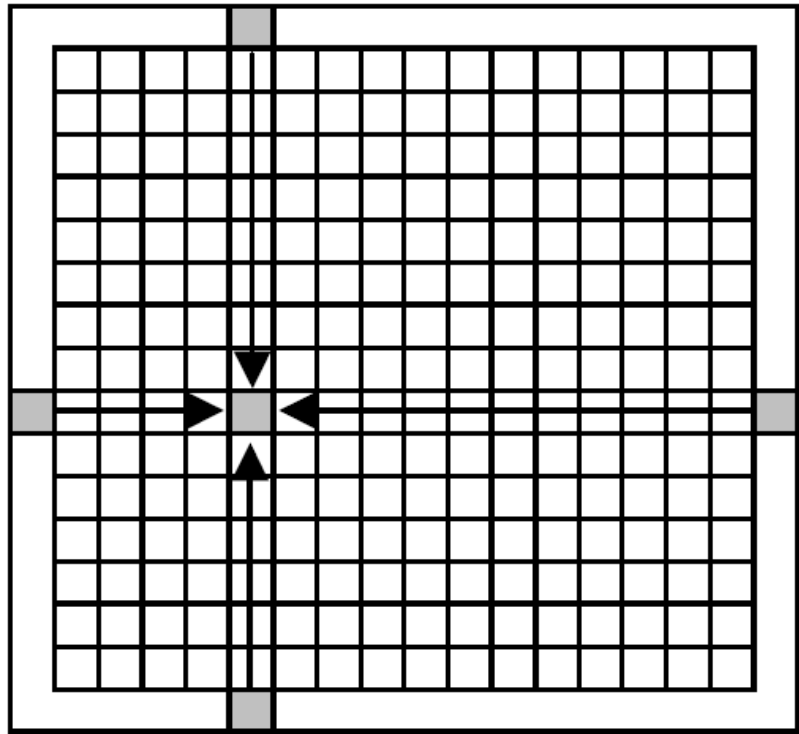
Decoded (err.)



"Copy" concealment

# Simple intra concealment

- Weighted pixel averaging from neighbouring macroblock samples
- Neighbours have to be available
- If neighbours are also interpolated, prediction becomes worse



# Simple inter concealment

- Motion vectors tend to correlate in small regions and over a small number of pictures
- If motion vectors are lost, they may be predicted from the neighbouring blocks and/or the reference frame's co-located macroblocks
- Motion vector prediction (based on median, average or similar techniques) often fails
- In some cases: copy co-located reference block

# Advanced concealment I

- Based on scene cut detection to force zero motion vectors for lost blocks

Picture n-1

20% loss



Picture n

20% loss



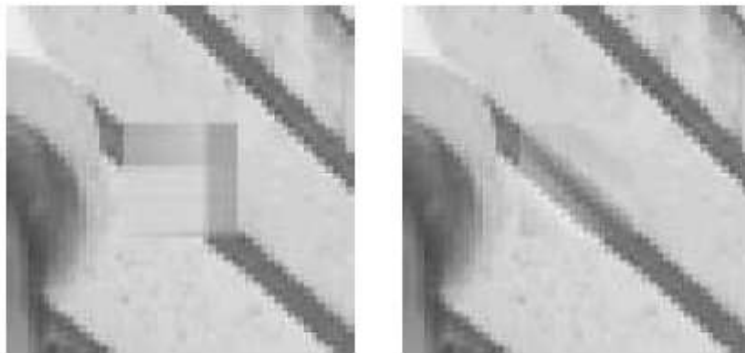
Original

Decoded (err.)

Concealed

# Advanced concealment II

- Dominant edge detection from neighbouring macroblocks for directional interpolation



Weighted averaging vs. edge detection



# Advanced concealment III

- Theoretical methods not for practical use
- Example: determine regions of interest (green box) in the picture through subjective tests and force intra prediction for affected blocks



# Loss measurement

- Complete loss of macroblocks or whole slices is hard to measure (as effect on the picture(s))
- Complete loss is nearly always noticeable, but concealment can hide it up to a certain extent
- Y-PSNR and SSIM make sense in error concealed pictures, but not in lost ones
- Measuring quality of pictures with completely lost macroblocks or slices is difficult

# Practical tasks I

- Handling uncompressed (YUV) video files
  - Opening, viewing and comparing
  - File size calculations and considerations
- Getting to know x264, an H.264 encoder
  - Basic H.264 encoding (default settings)
  - Original/output file comparison
  - Effect of options on coding time and quality
  - Output file formats and compatibility

# Practical tasks II

- Getting to know the testbed for error resilience
  - “Network” simulator with virtual, error prone transmission channel (on a NALU basis)
  - Extended version of x264 with error resilience tools
  - Extended version of ffmpeg with error concealment
- Testing effects of error resilience tools (increase in bit rate, increase in encoding time)
- Testing effects of error concealment methods (loss prevention, method comparison)

**Thank you for your attention!**

Questions?

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